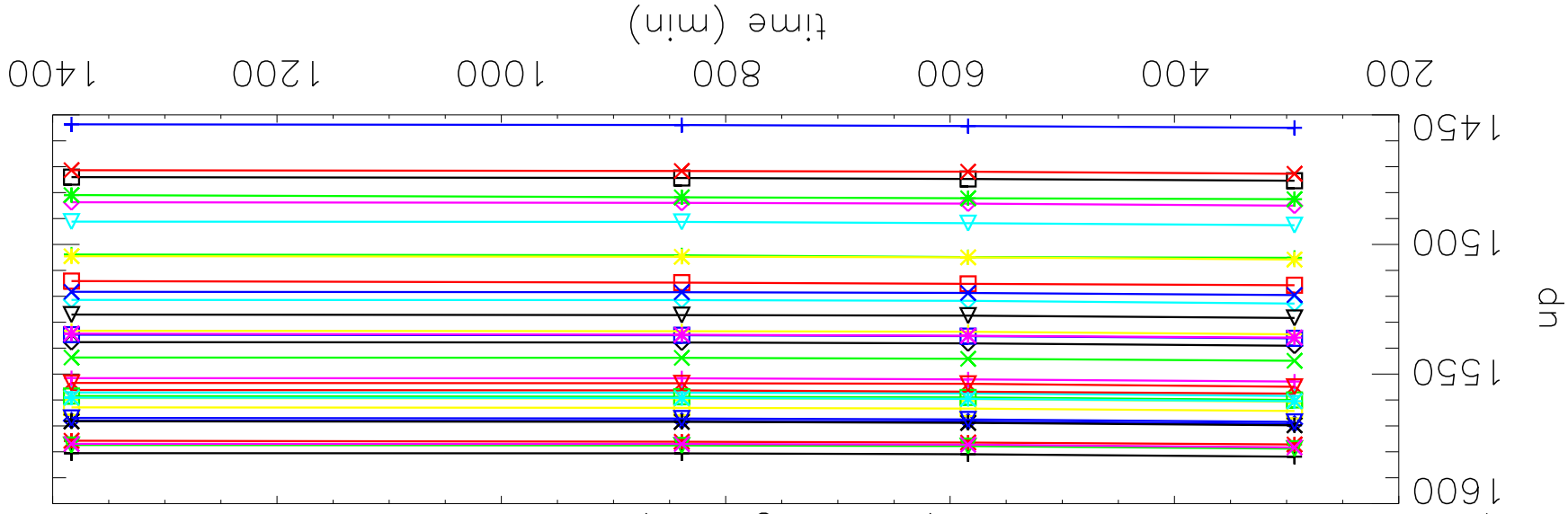
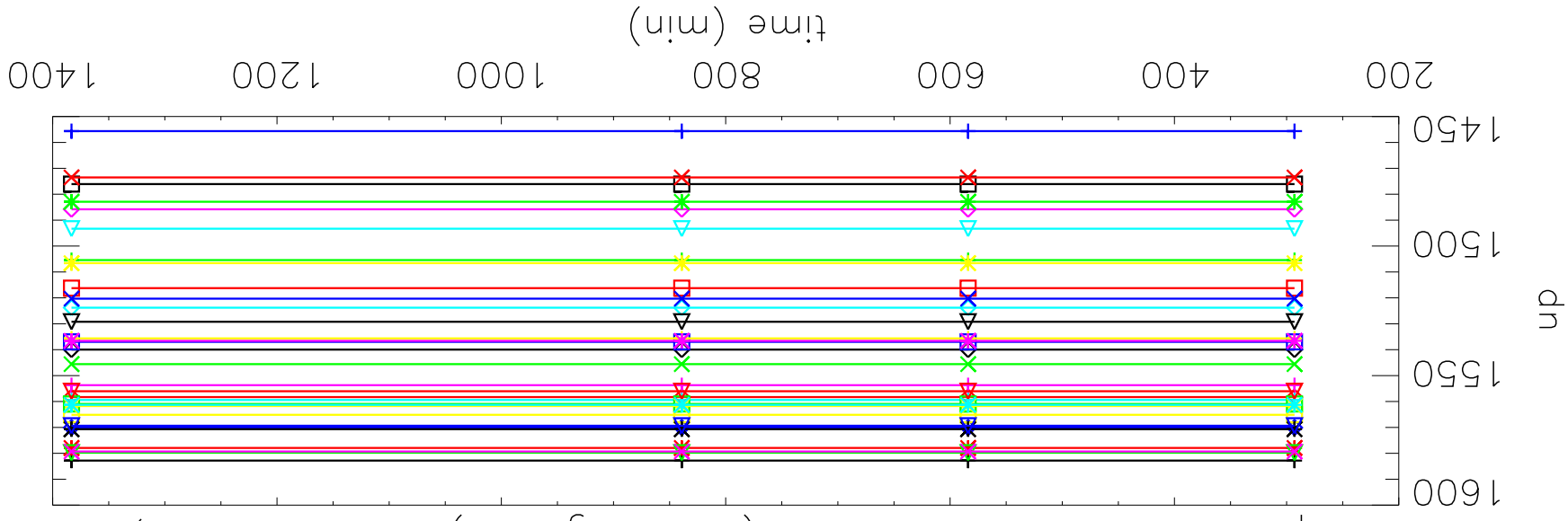


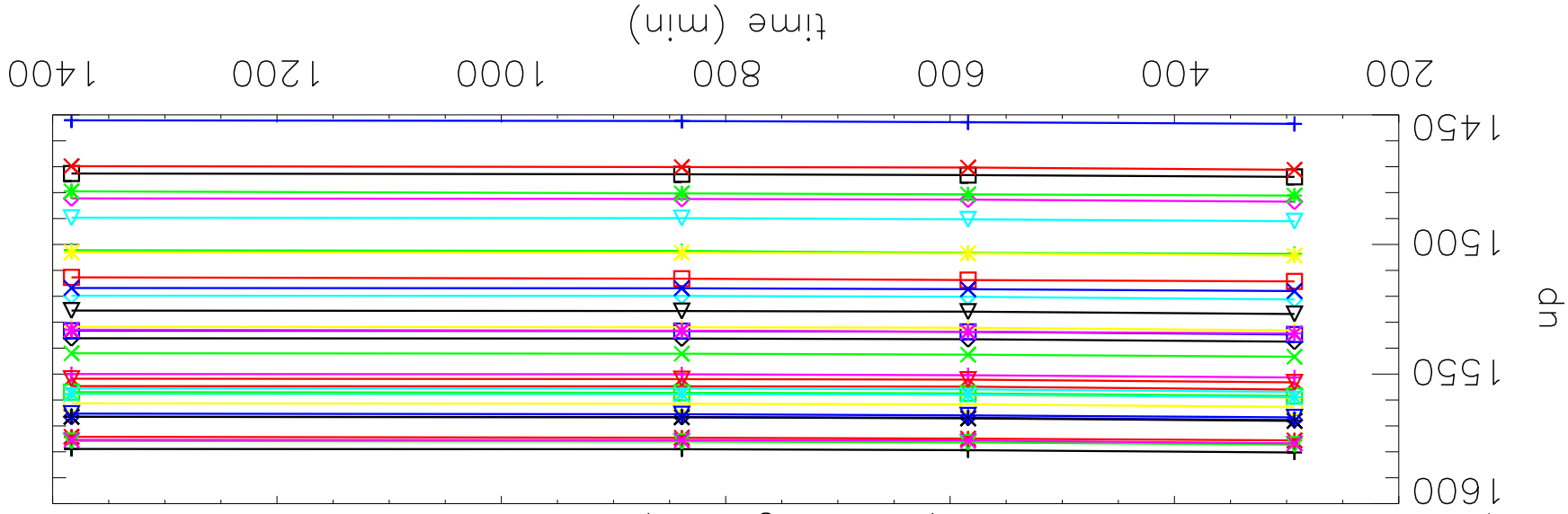
RVS repeated measurements (–8 degrees) versus time, 11 HAM A Int-time=



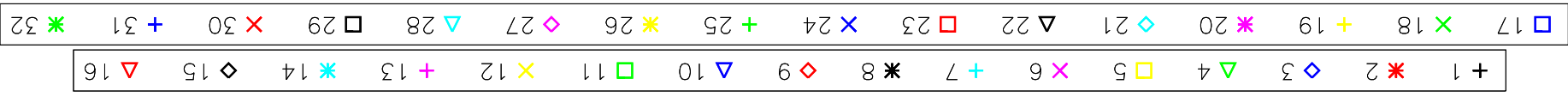
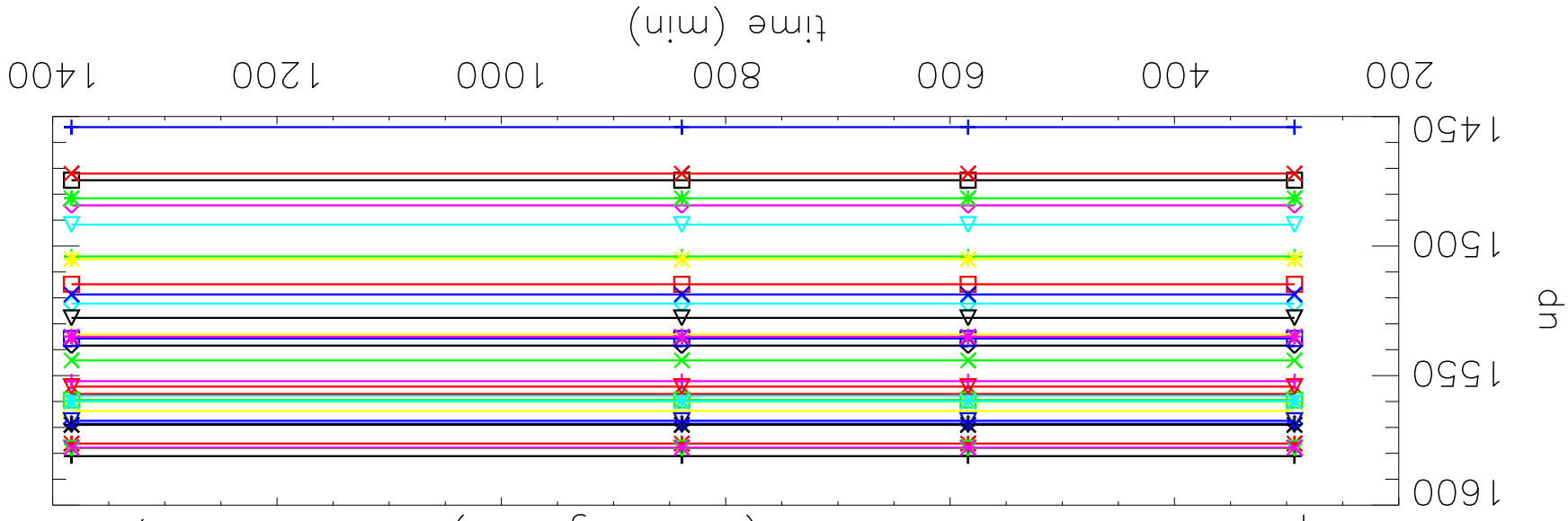
Drift Corrected RVS repeated measurements (–8 degrees) versus time, 11 HAM A Int-time=



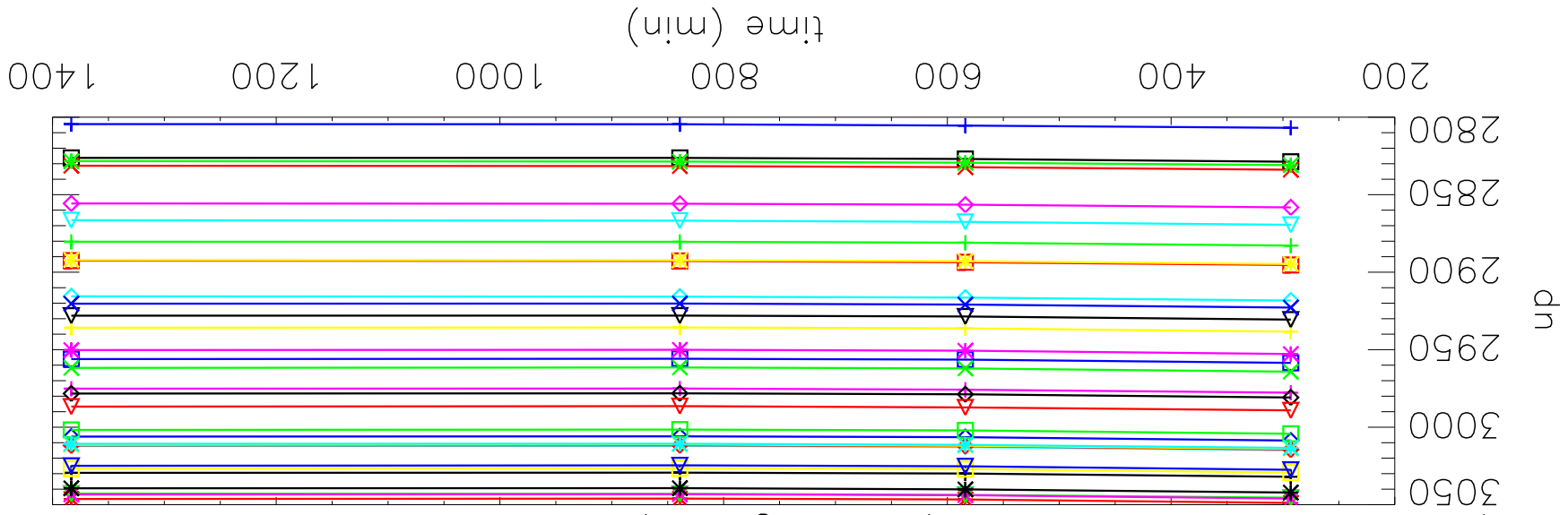
RVS repeated measurements (–8 degrees) versus time, 11 HAM B Int-time=



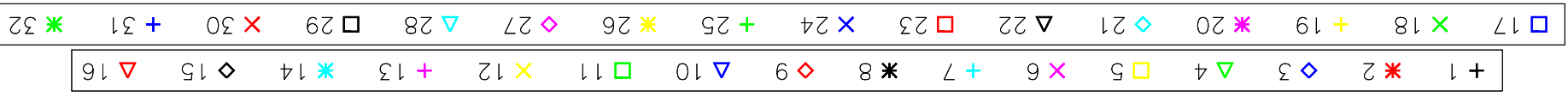
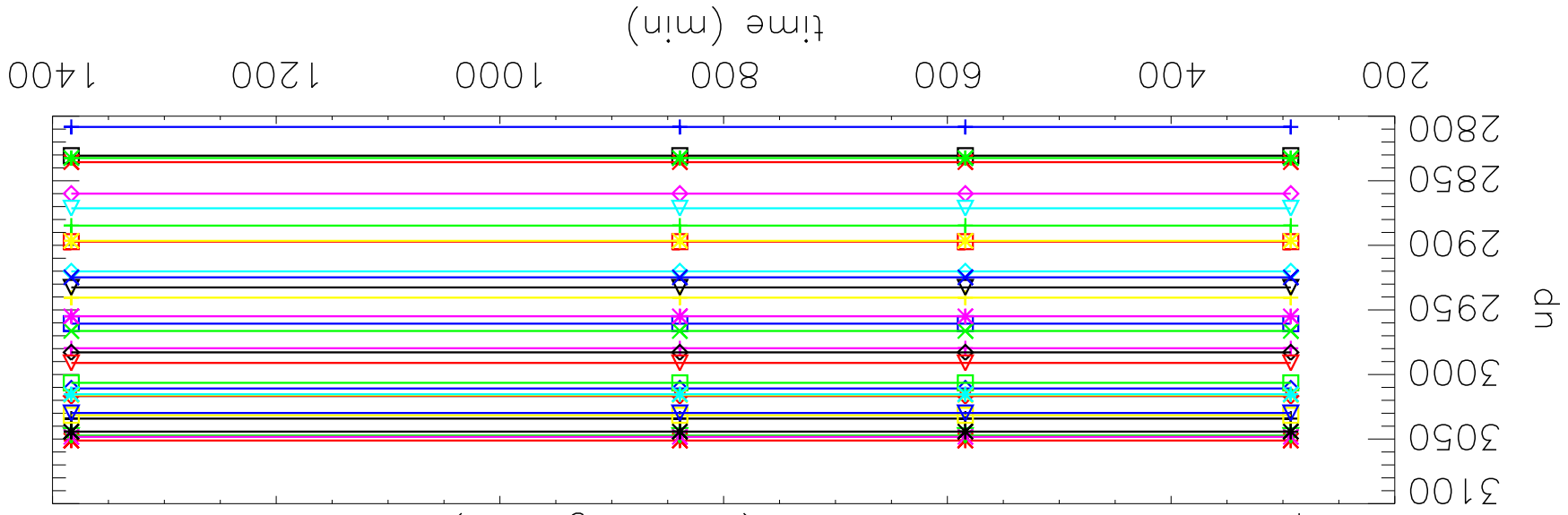
Drift Corrected RVS repeated measurements (–8 degrees) versus time, 11 HAM B I



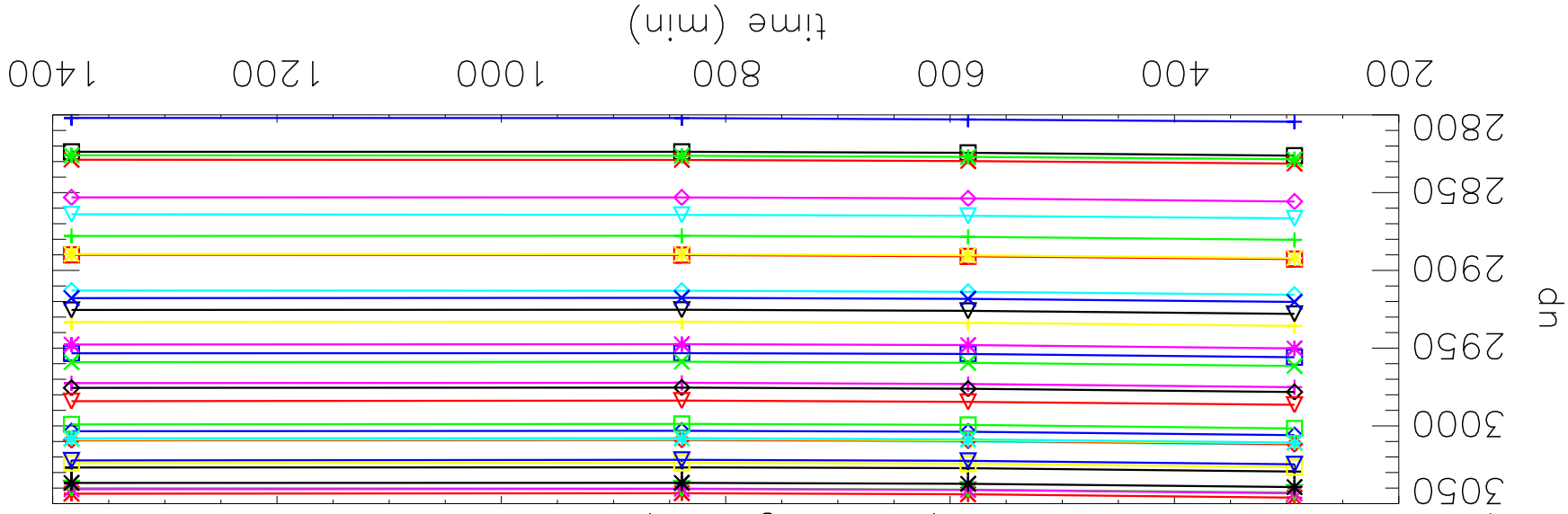
RVS repeated measurements (–8 degrees) versus time, 12 HAM A Int Time=



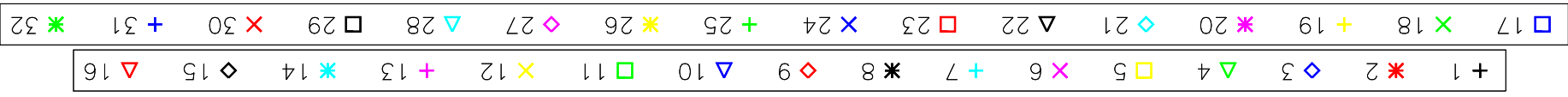
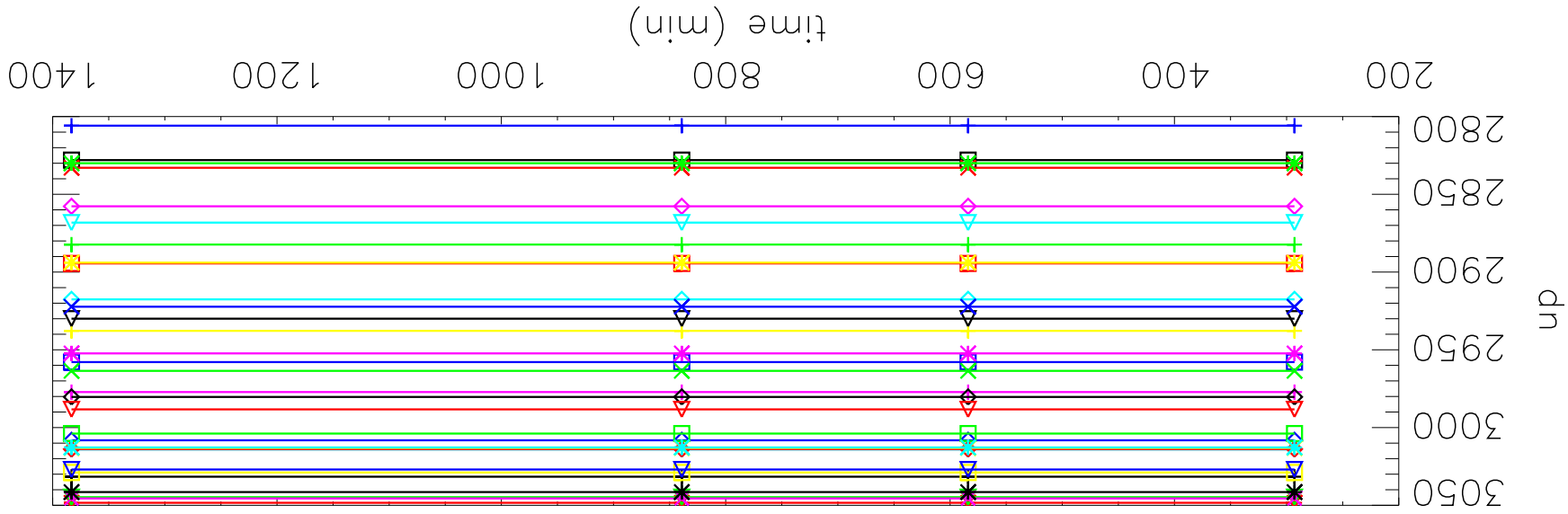
Drift Corrected RVS repeated measurements (–8 degrees) versus time, 12 HAM A Int



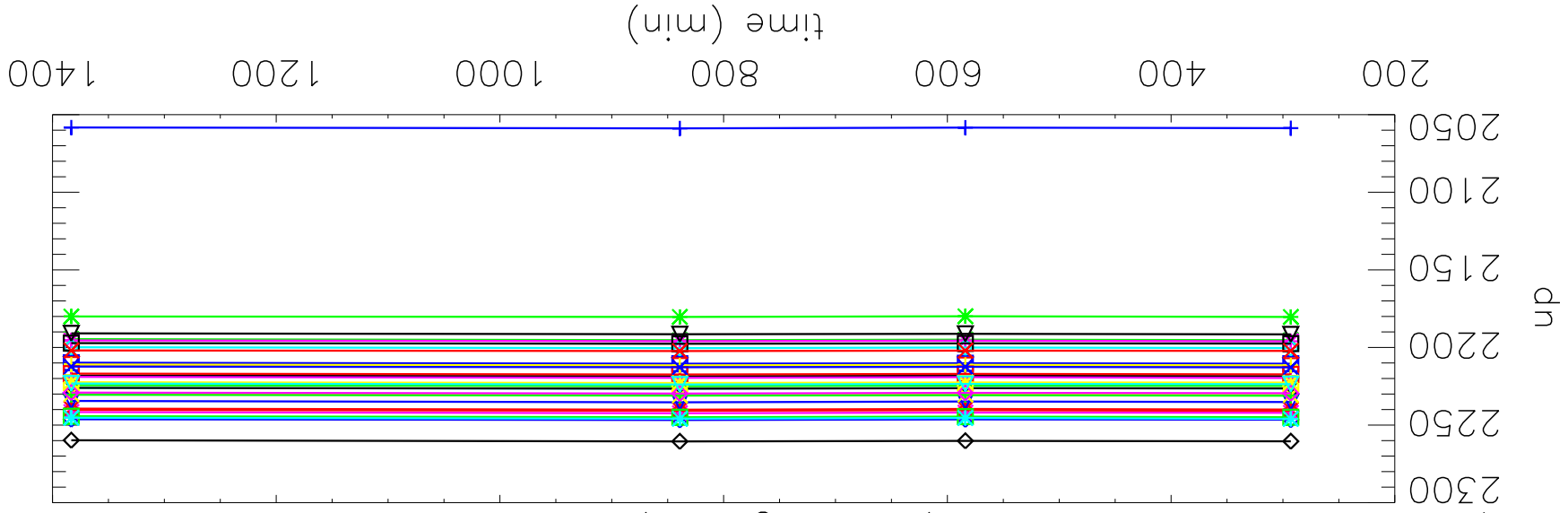
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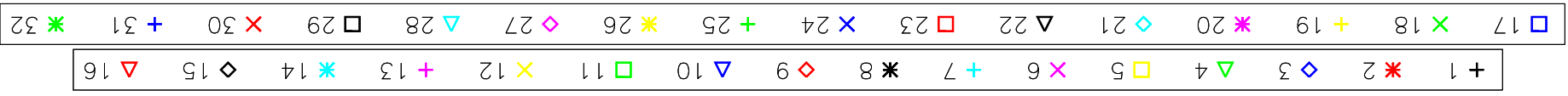
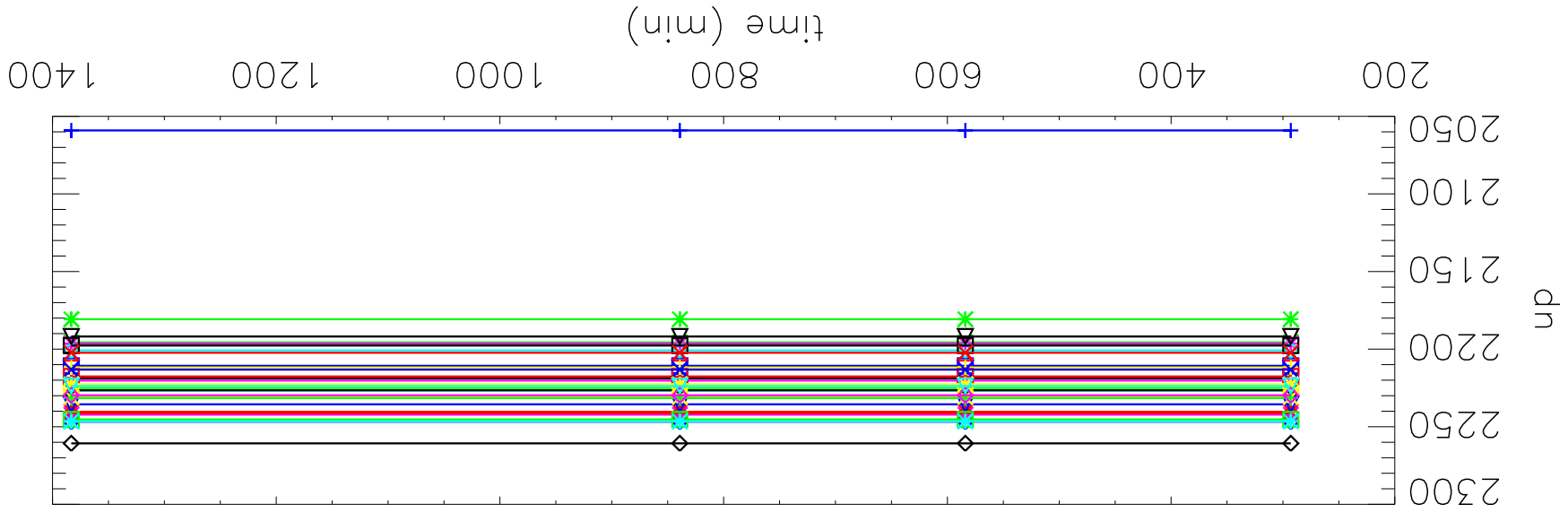
Drift Corrected RVS repeated measurements (–8 degrees) versus time, 12 HAM B I



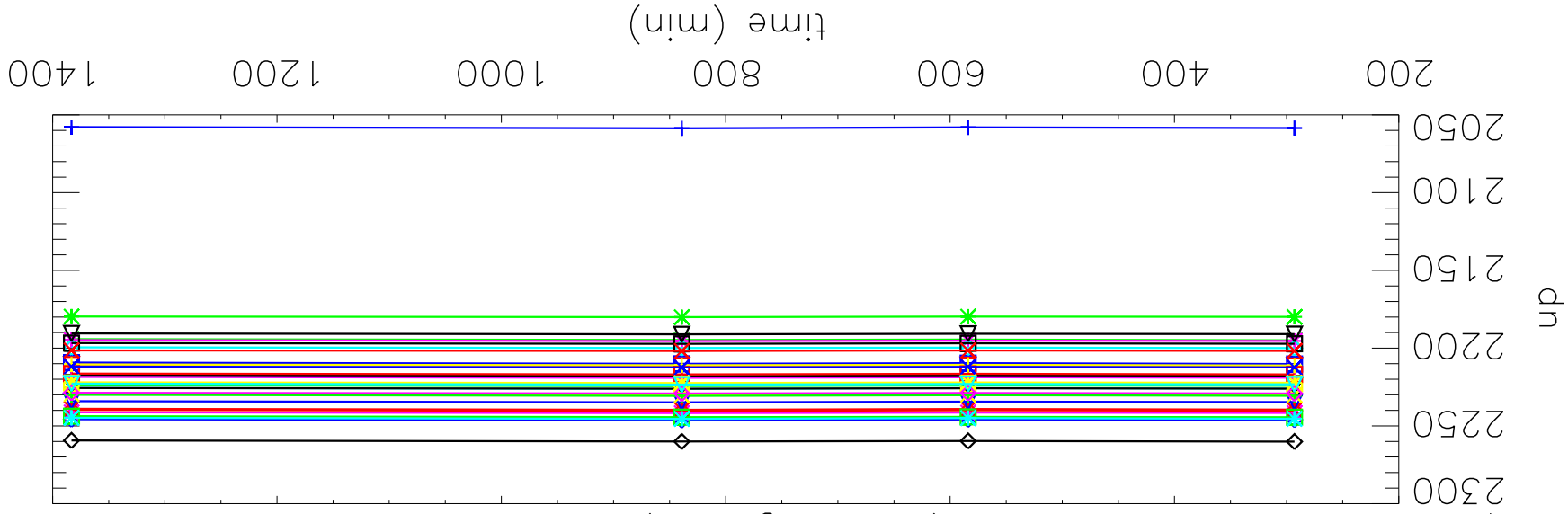
RVS repeated measurements (−8 degrees) versus time, 13 HAM A Int Time=



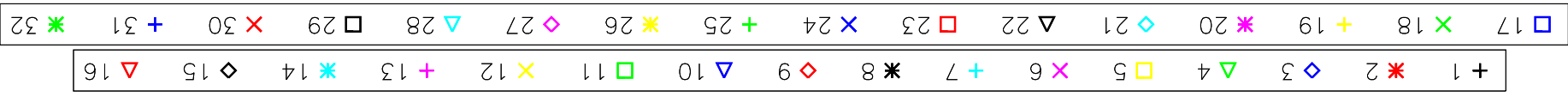
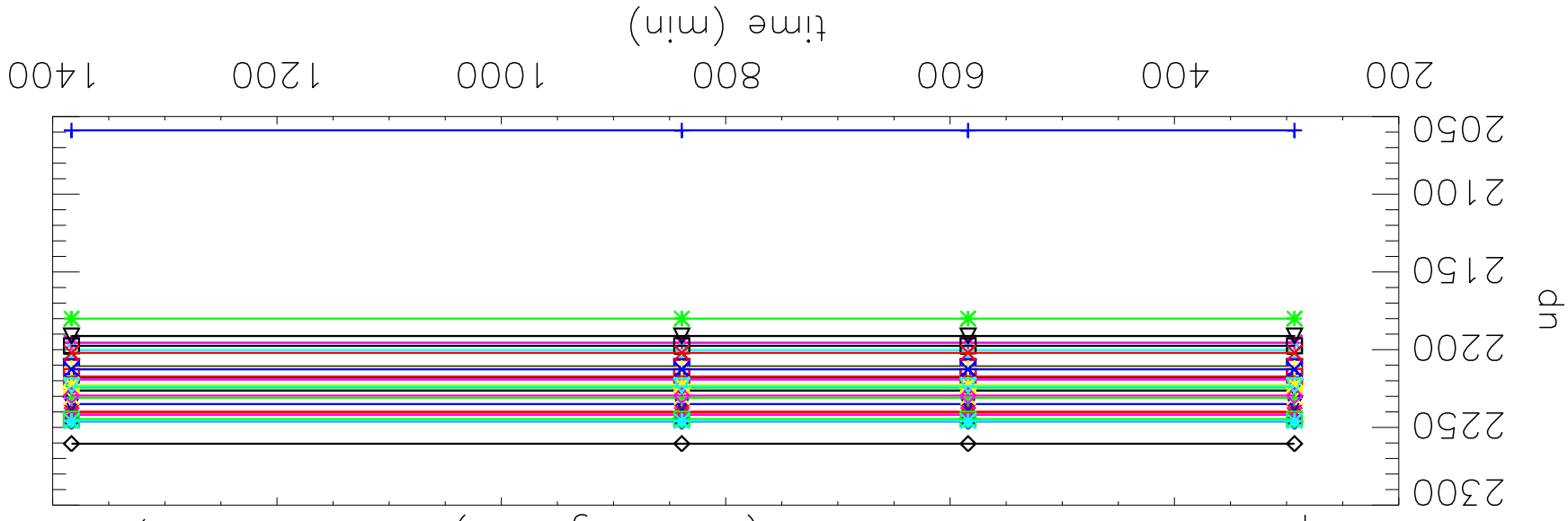
Drift Corrected RVS repeated measurements (−8 degrees) versus time, 13 HAM A Int



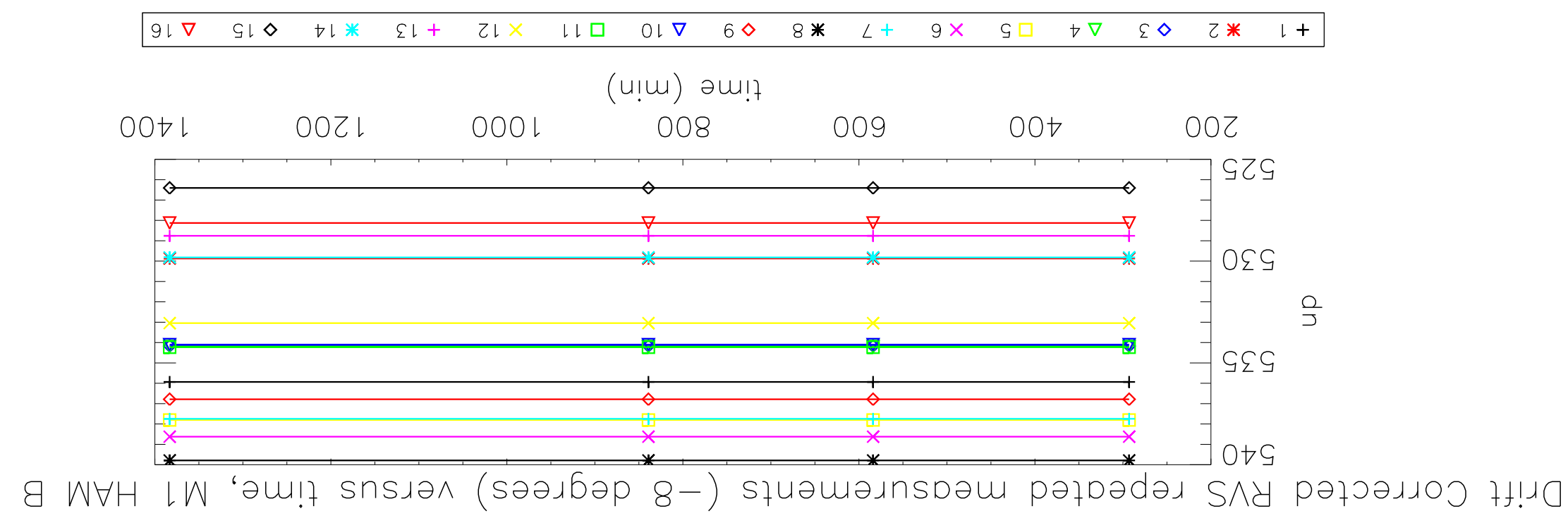
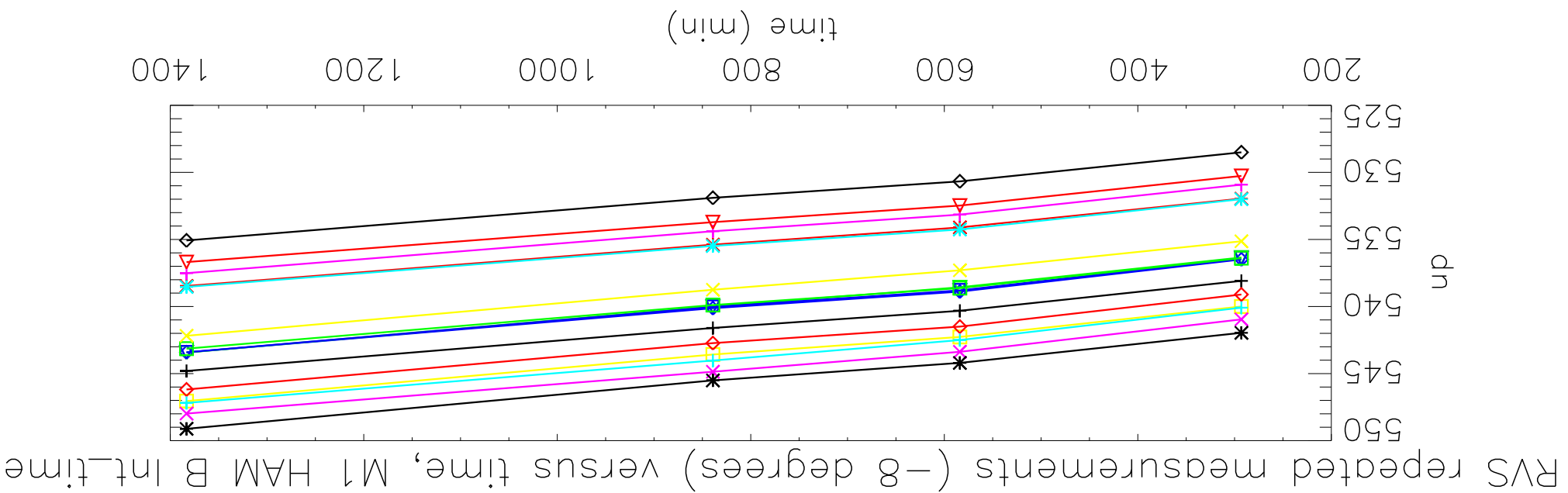
RVS repeated measurements (−8 degrees) versus time, 13 HAM B Int Time=

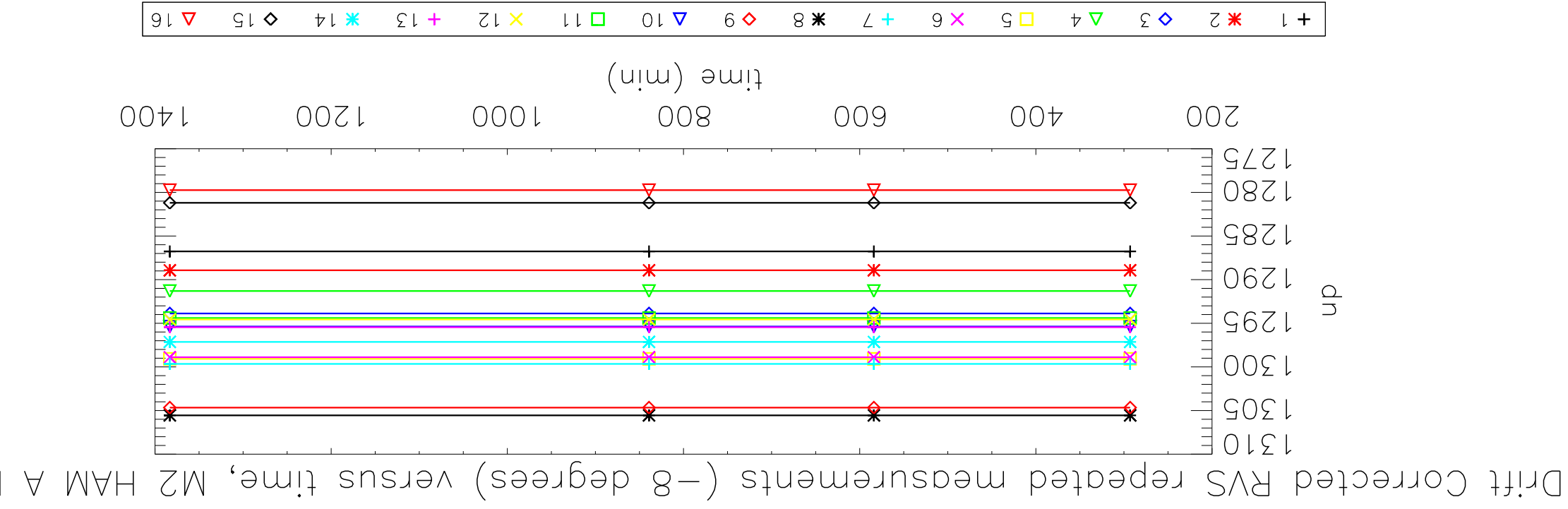
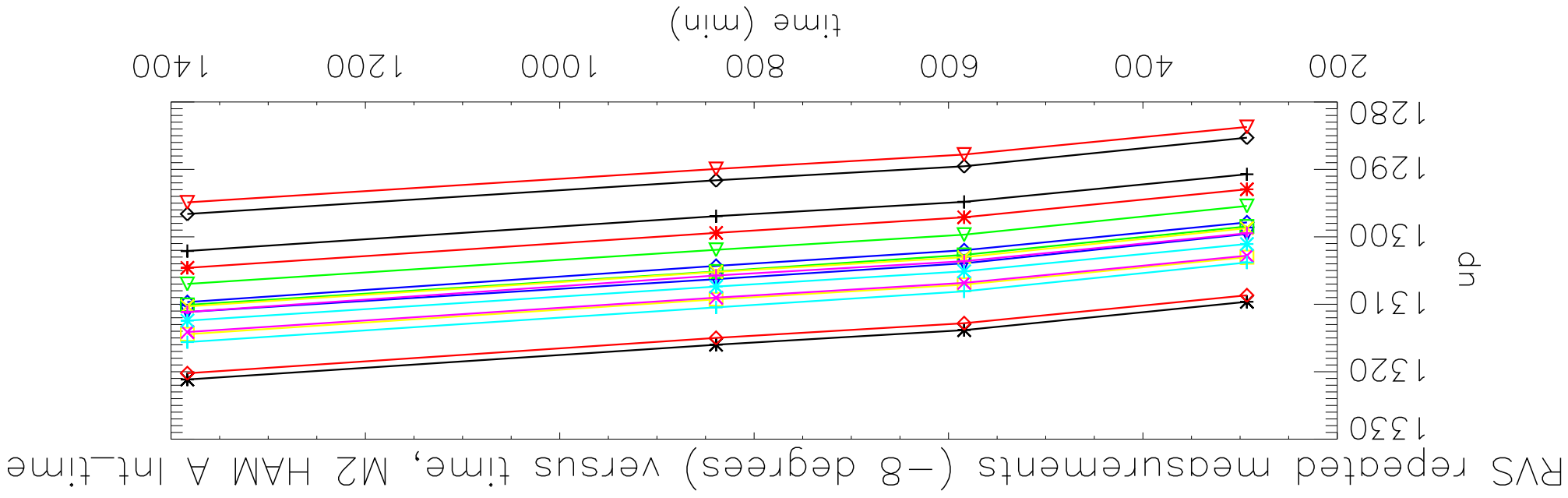


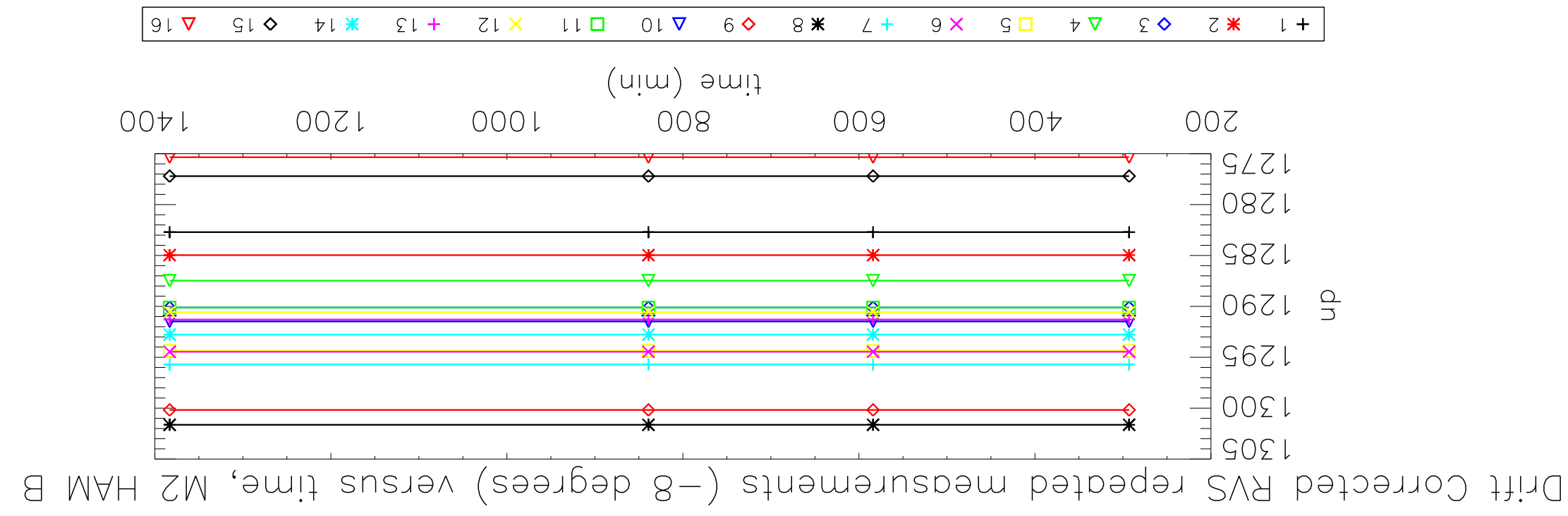
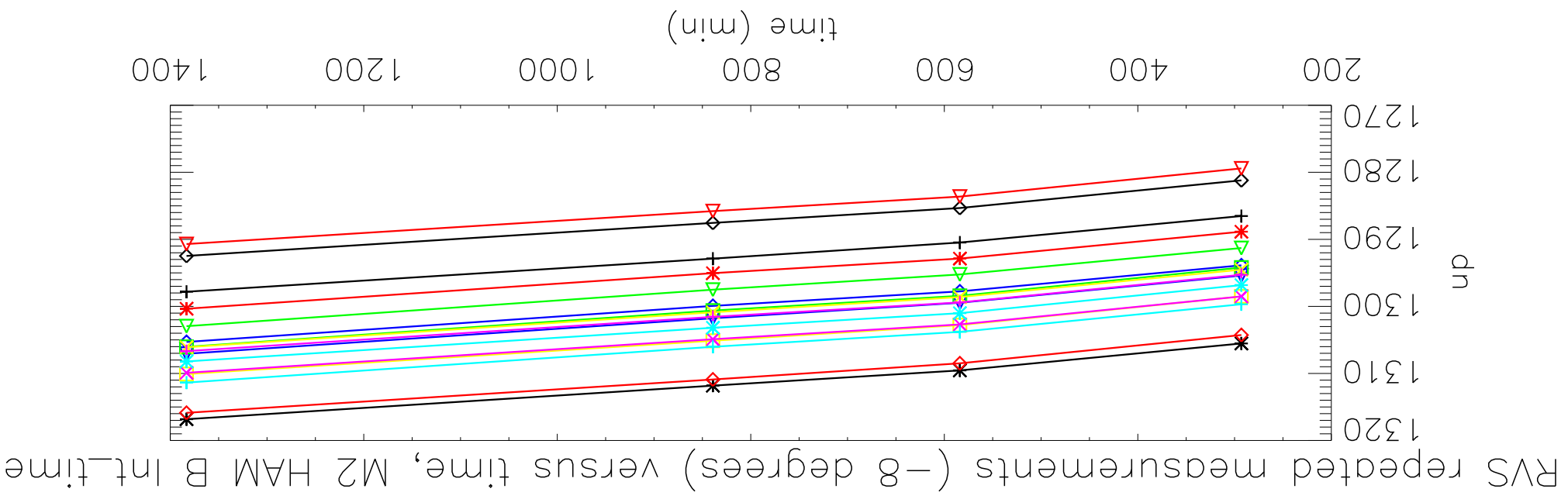
Drift Corrected RVS repeated measurements (−8 degrees) versus time, 13 HAM B I



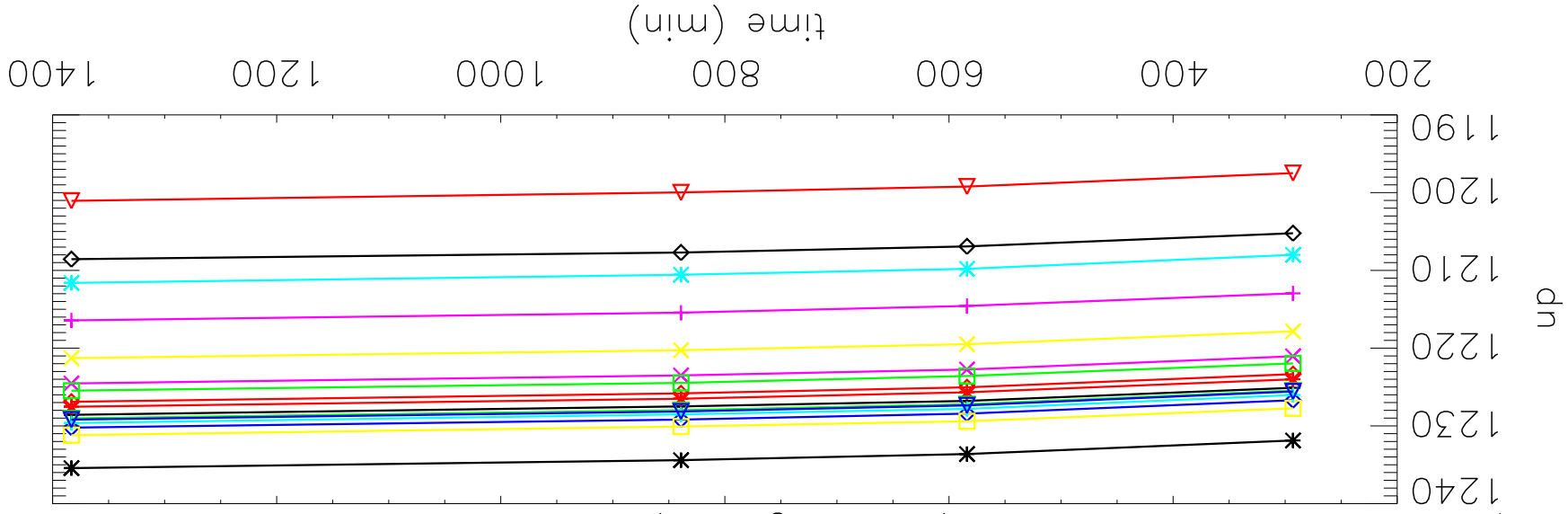




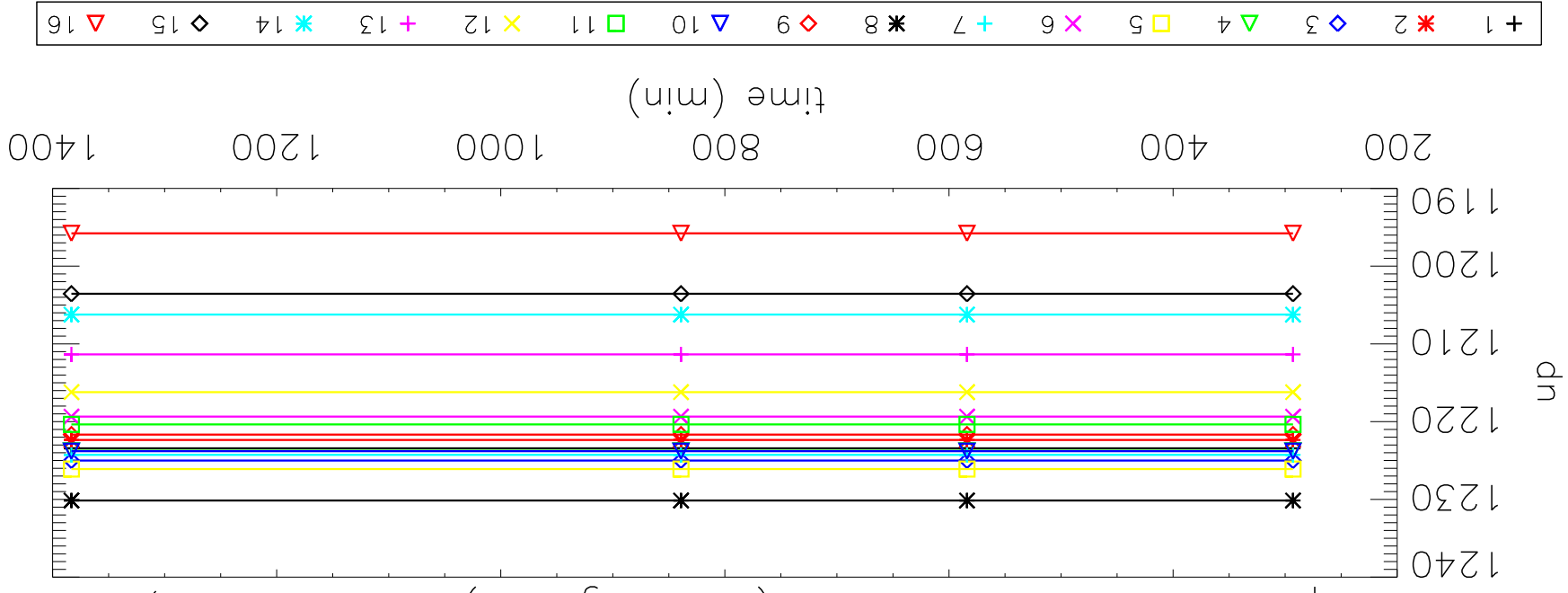




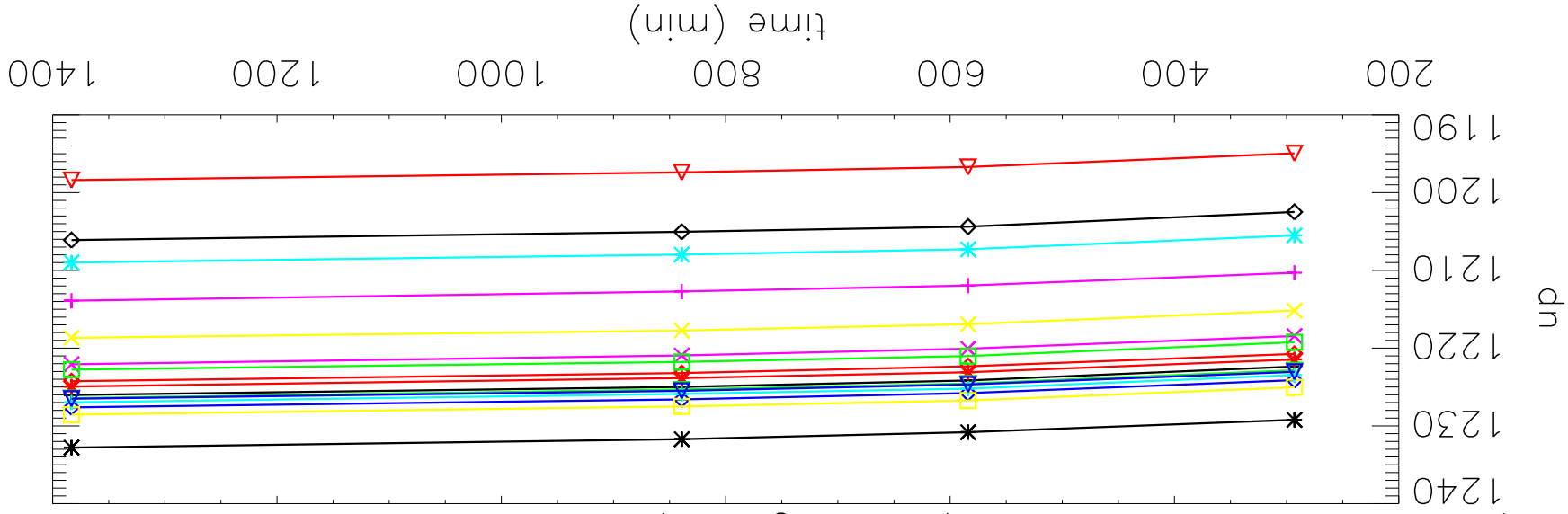
RVS repeated measurements (–8 degrees) versus time, M3 HAM A Int-Time



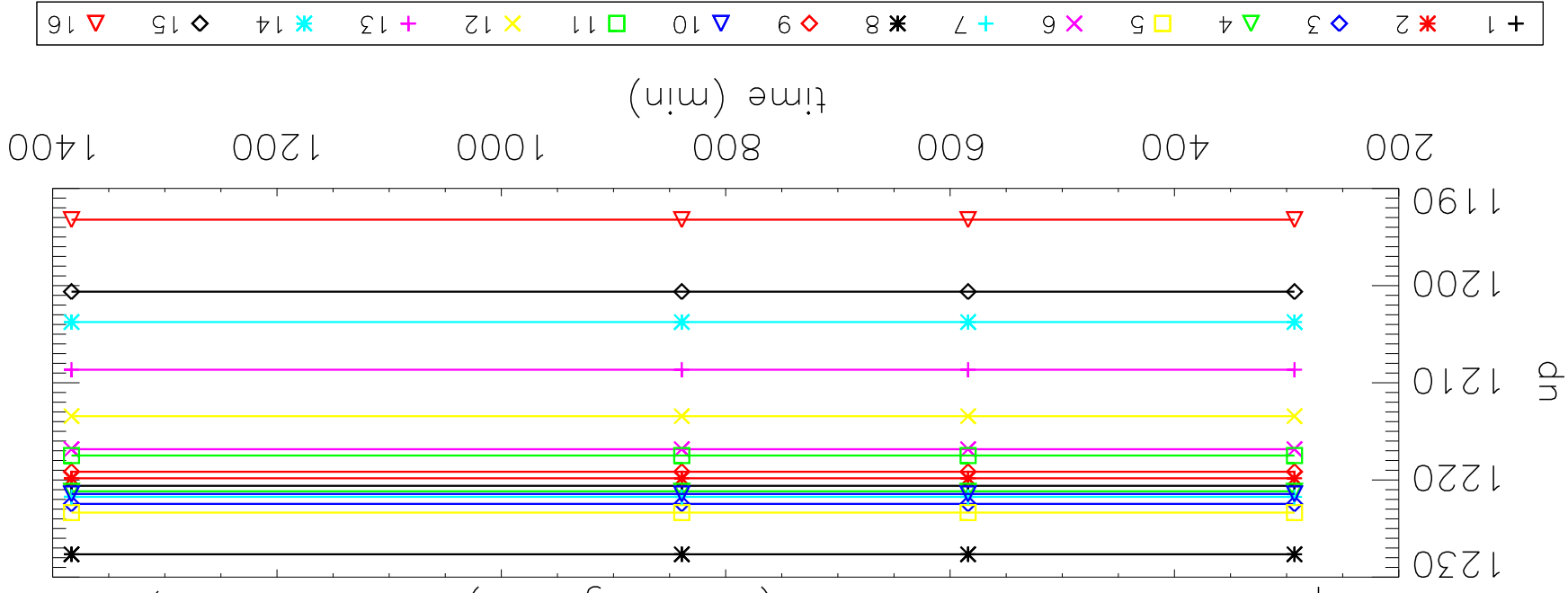
Drift Corrected RVS repeated measurements (–8 degrees) versus time, M3 HAM A Int-Time



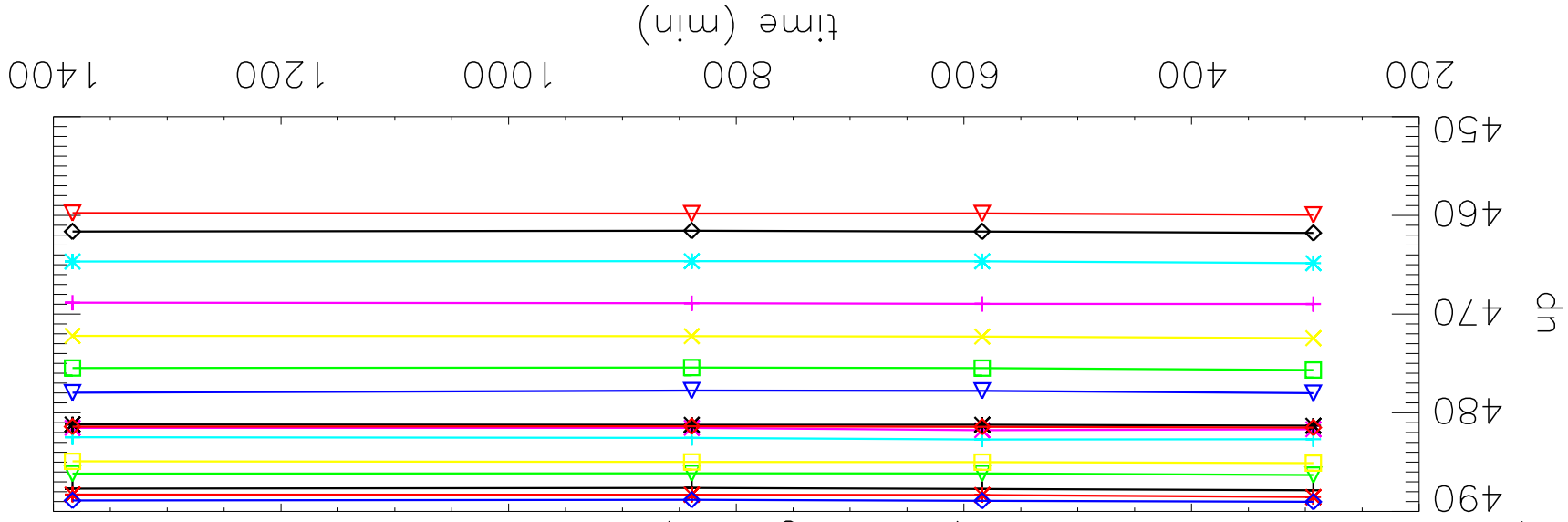
RVS repeated measurements (–8 degrees) versus time, M3 HAM B Int-Time



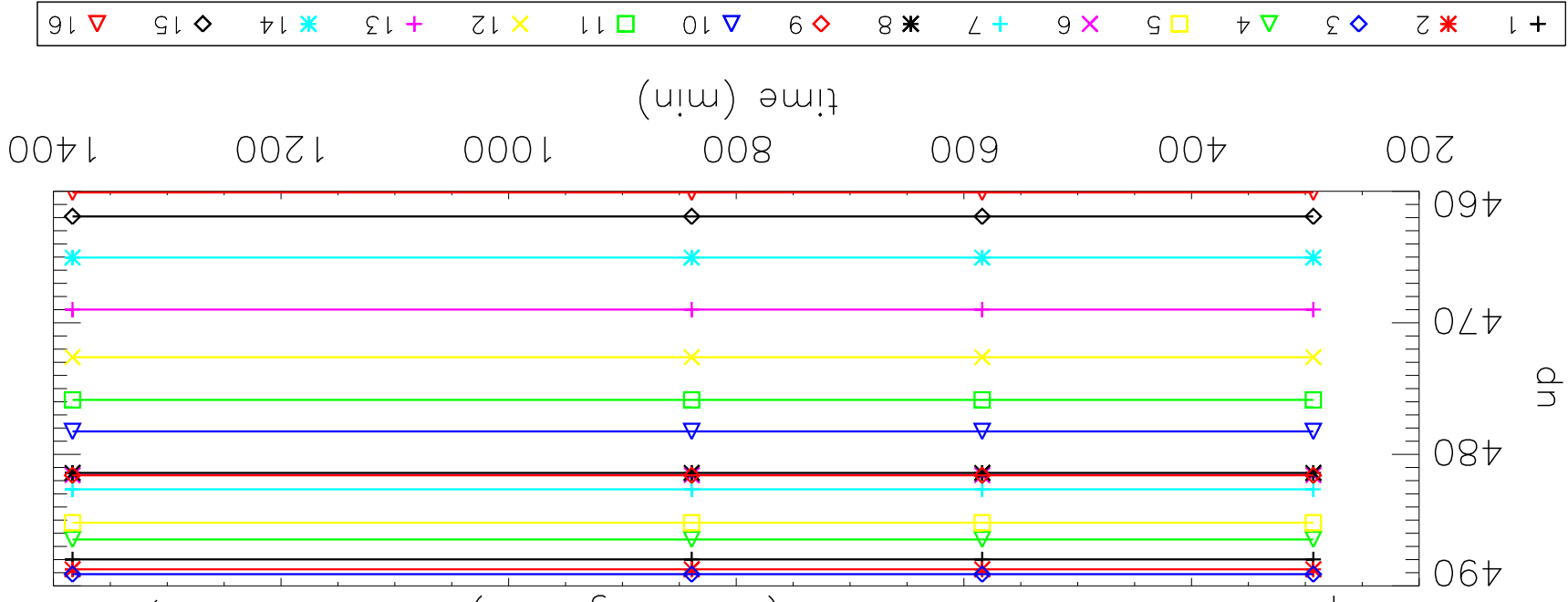
Drift Corrected RVS repeated measurements (–8 degrees) versus time, M3 HAM B

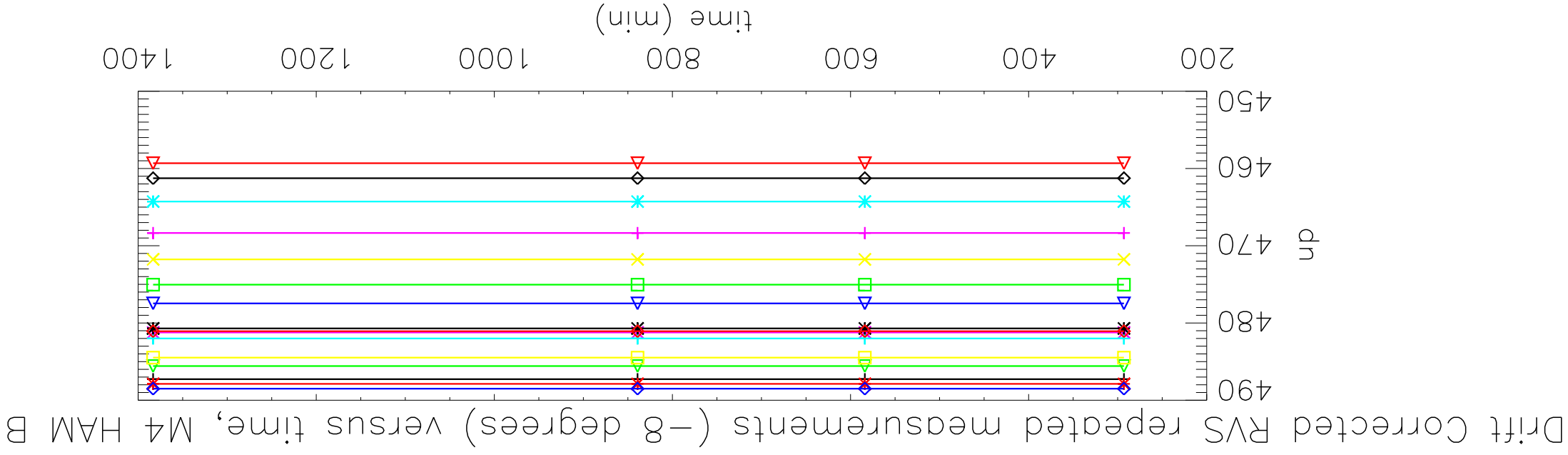
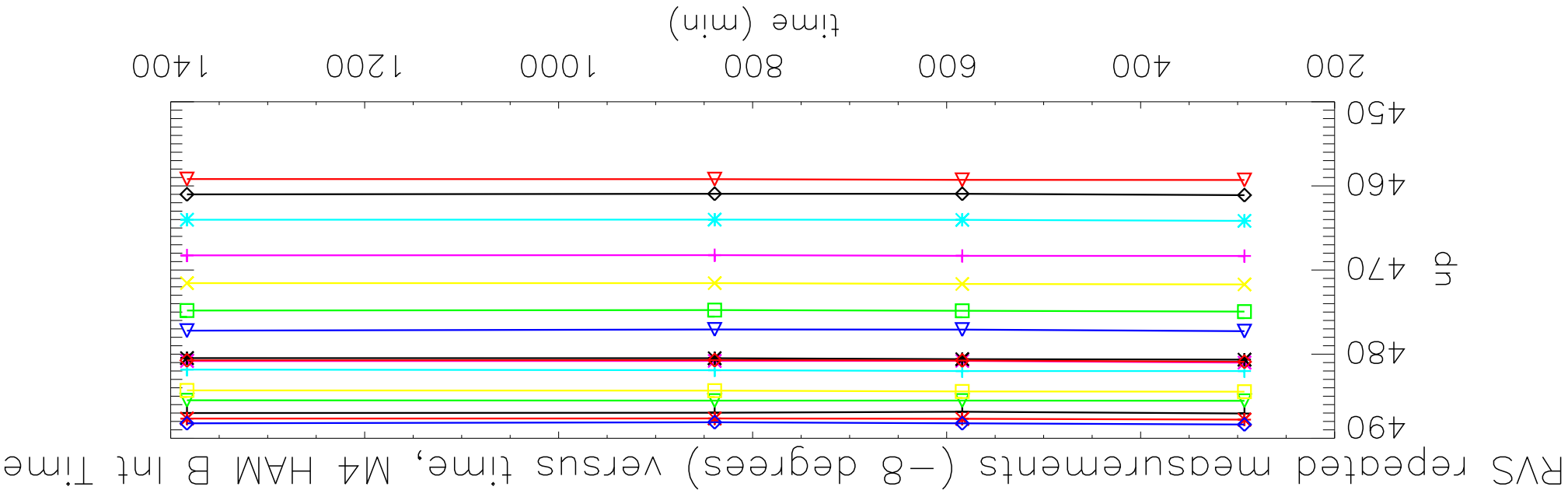


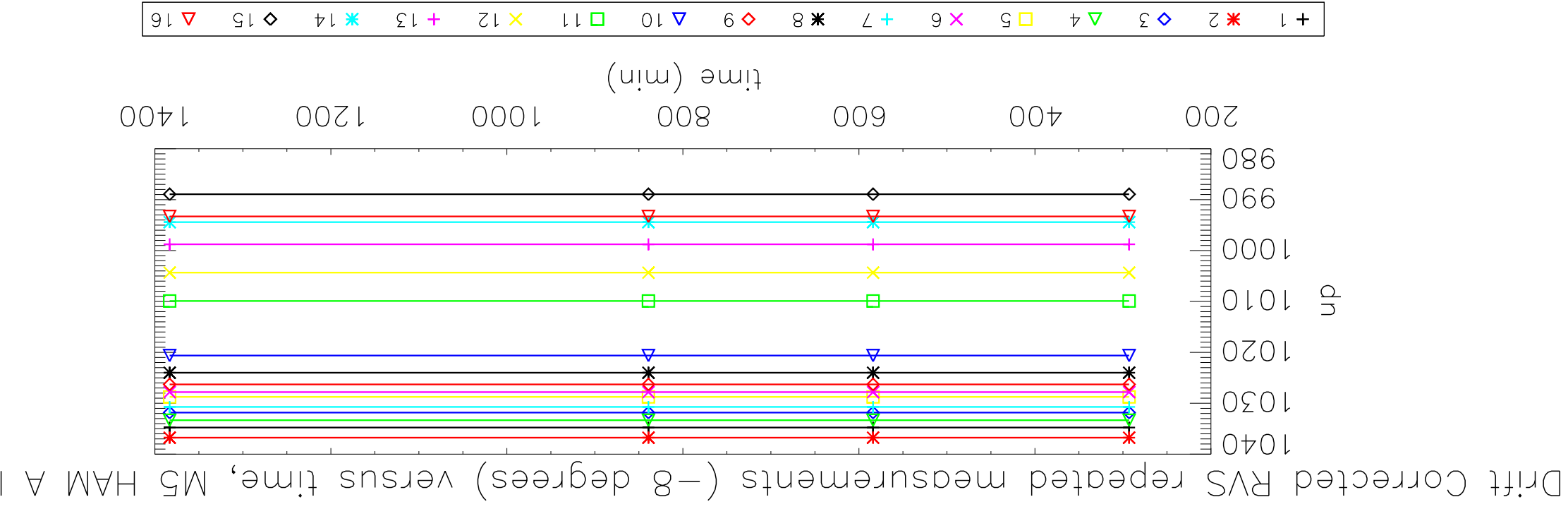
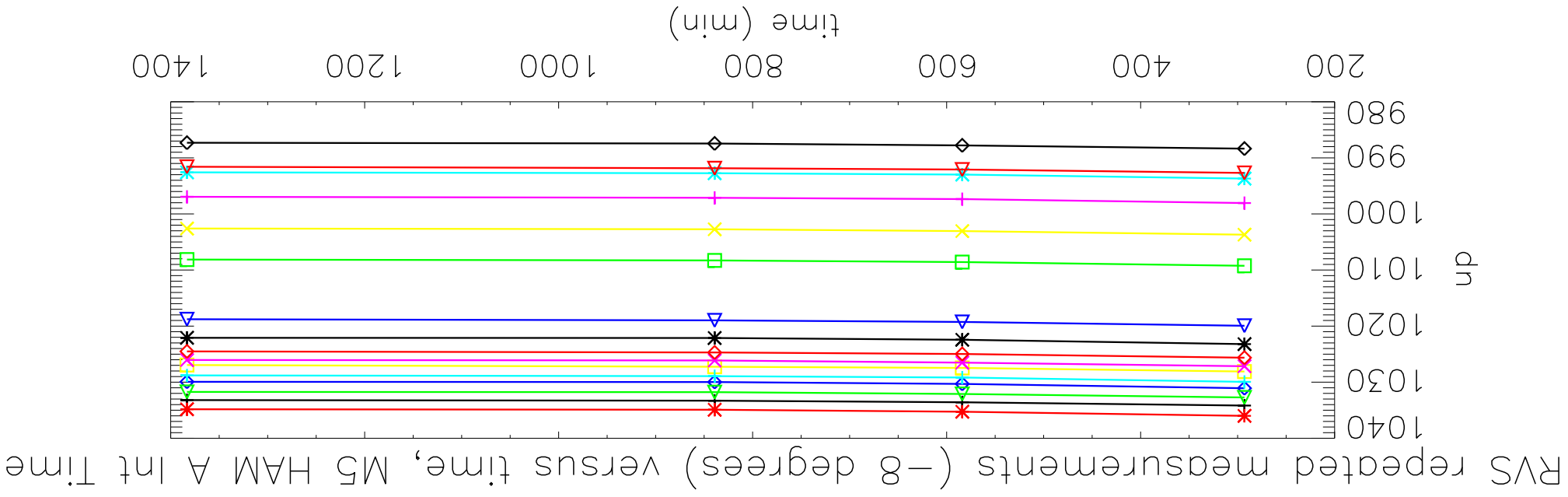
RVS repeated measurements (–8 degrees) versus time, M4 HAM A Int Time

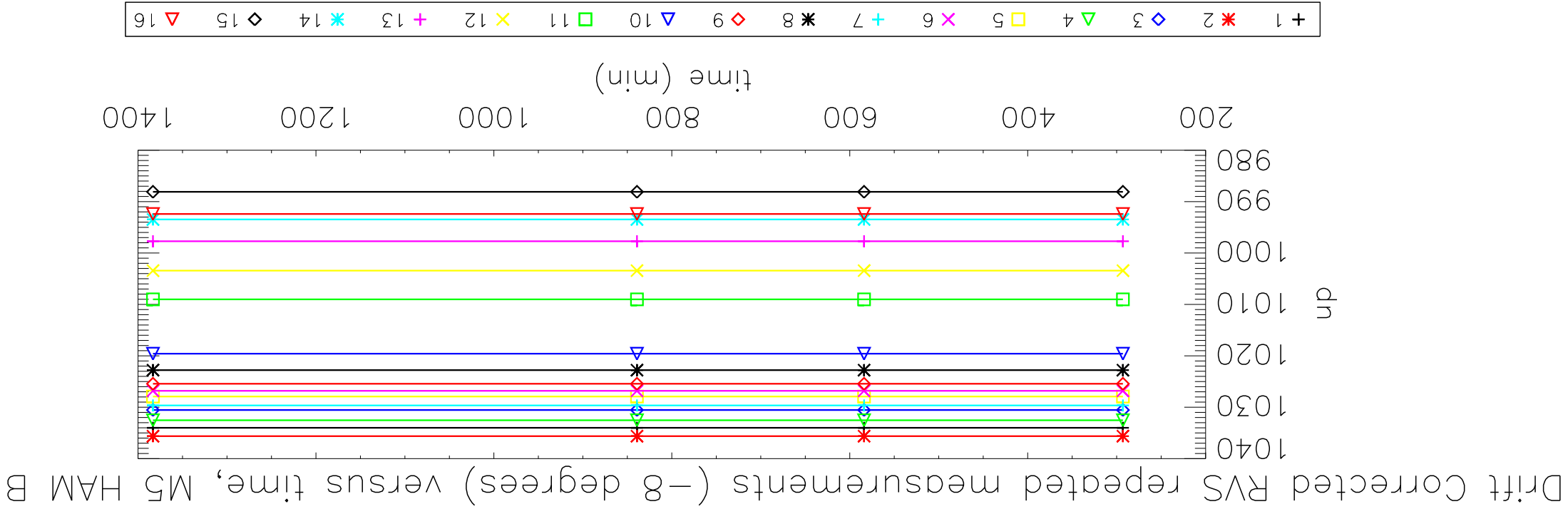
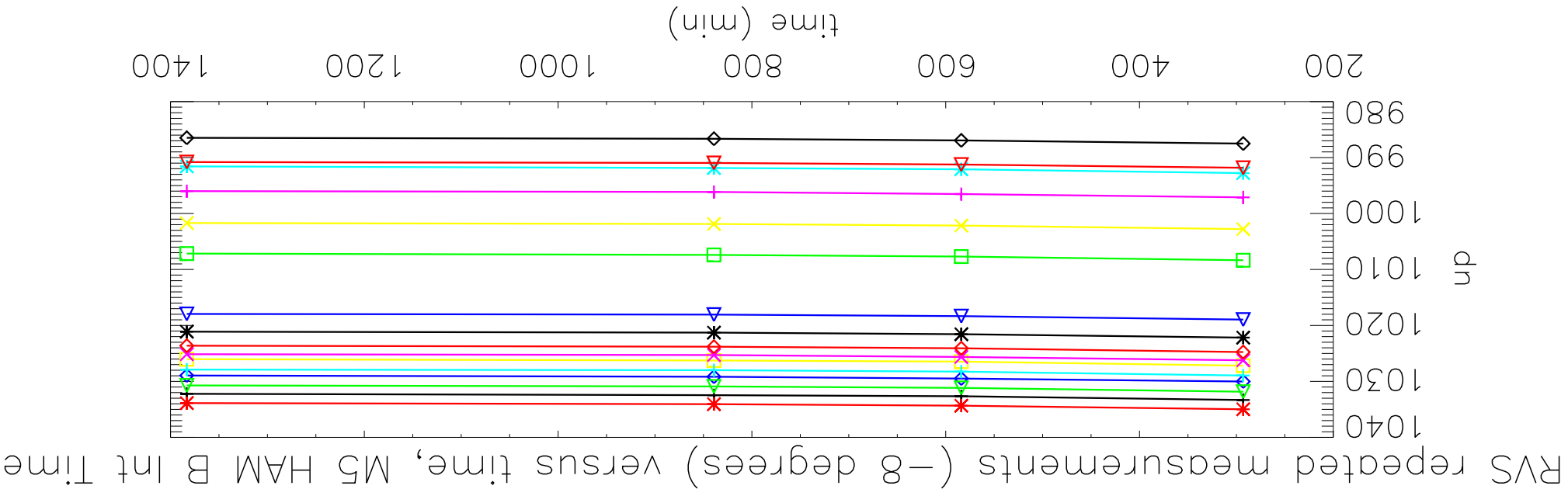


Drift Corrected RVS repeated measurements (–8 degrees) versus time, M4 HAM A Int Time

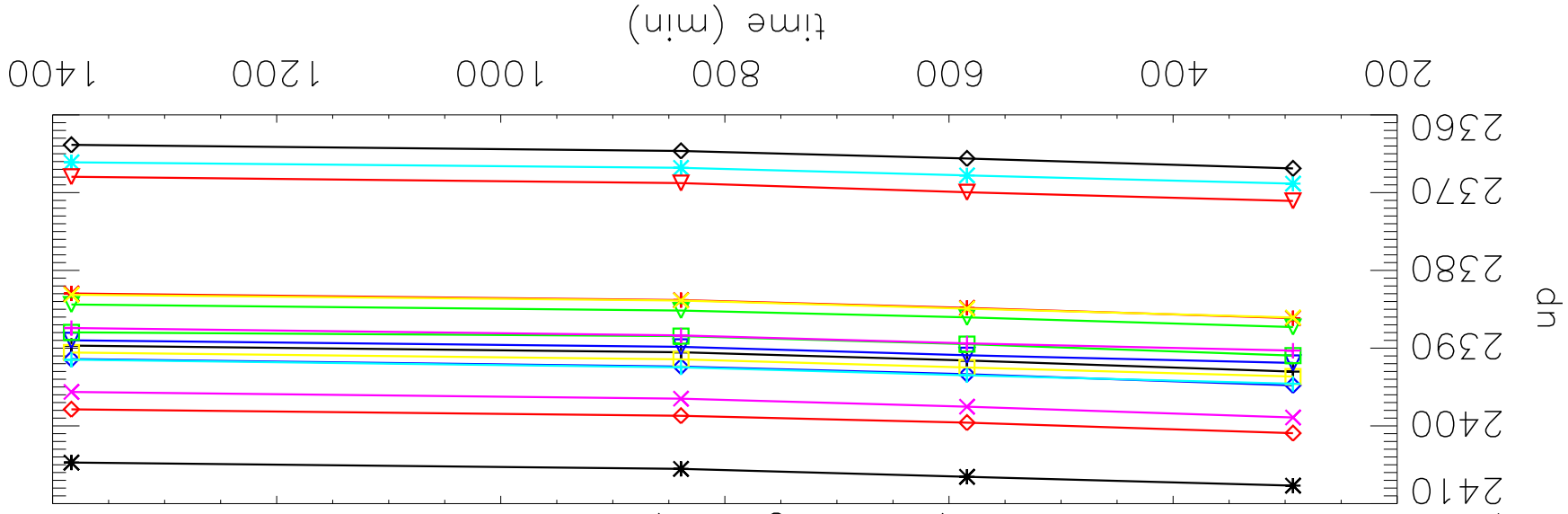




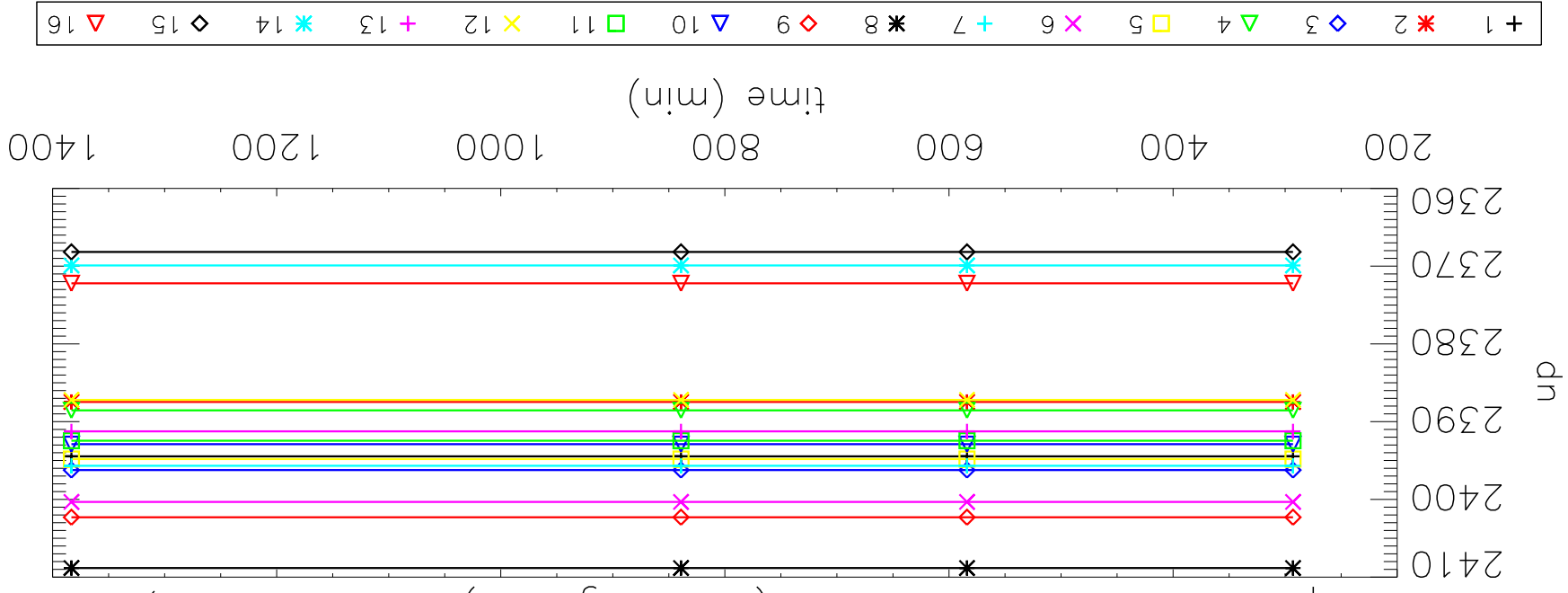


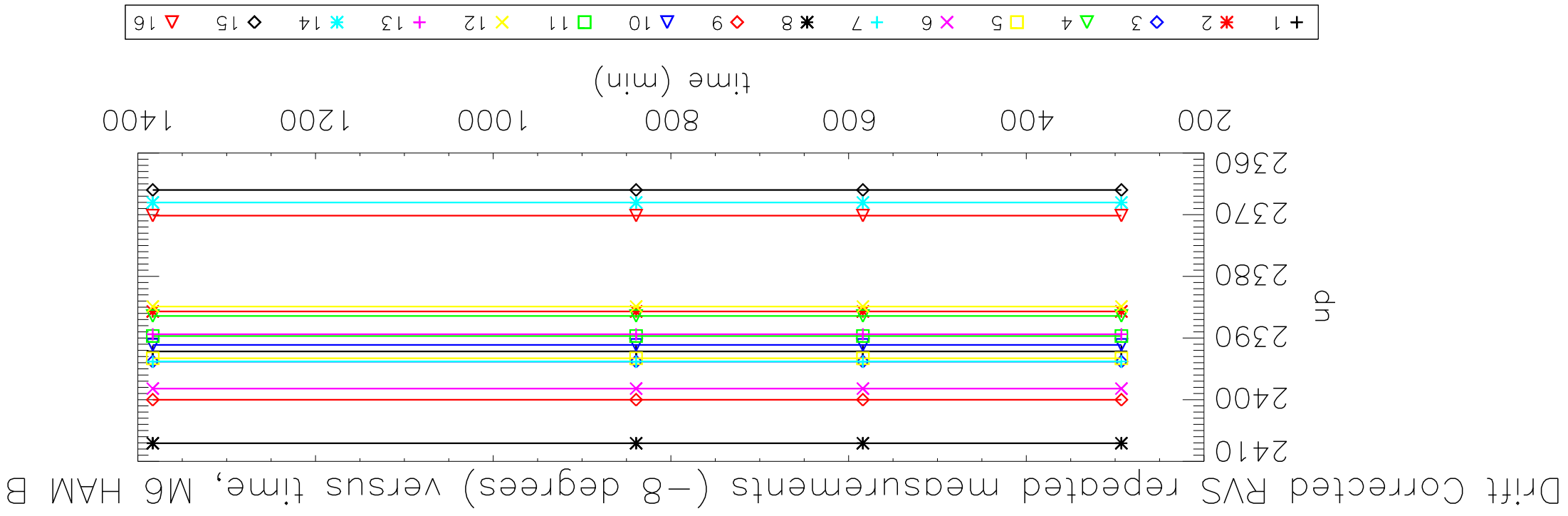
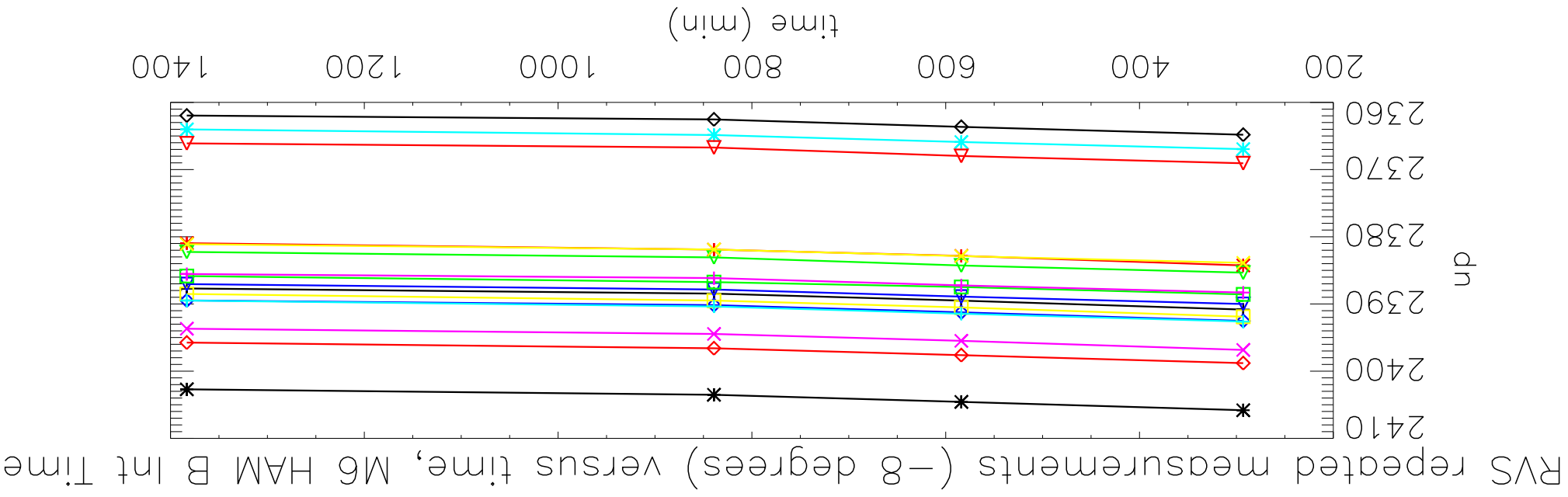


RVS repeated measurements (–8 degrees) versus time, M6 HAM A Int Time

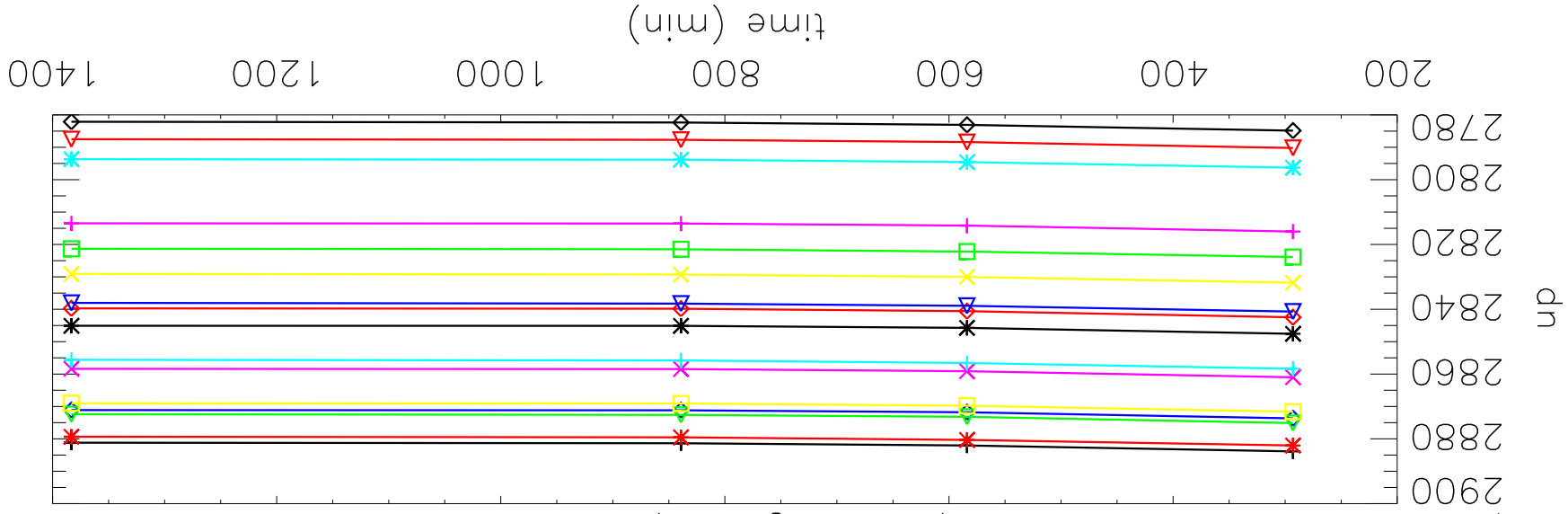


Drift Corrected RVS repeated measurements (–8 degrees) versus time, M6 HAM A Int Time

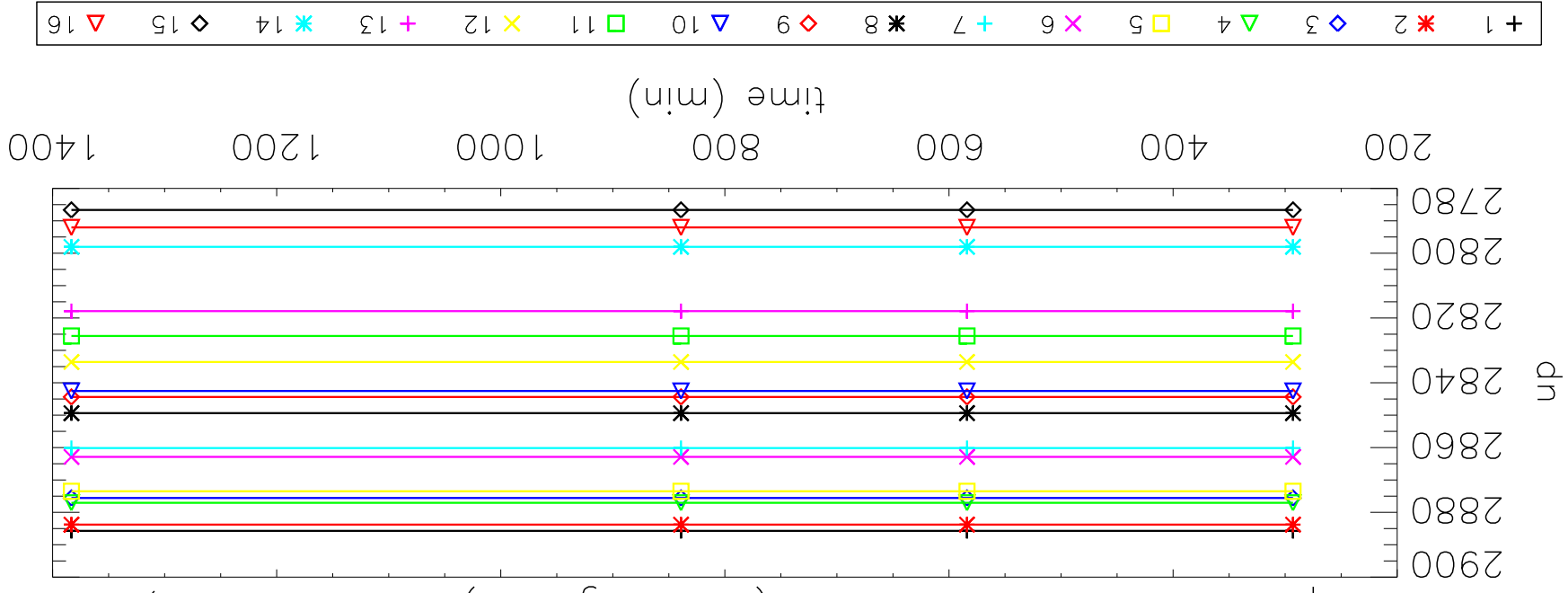


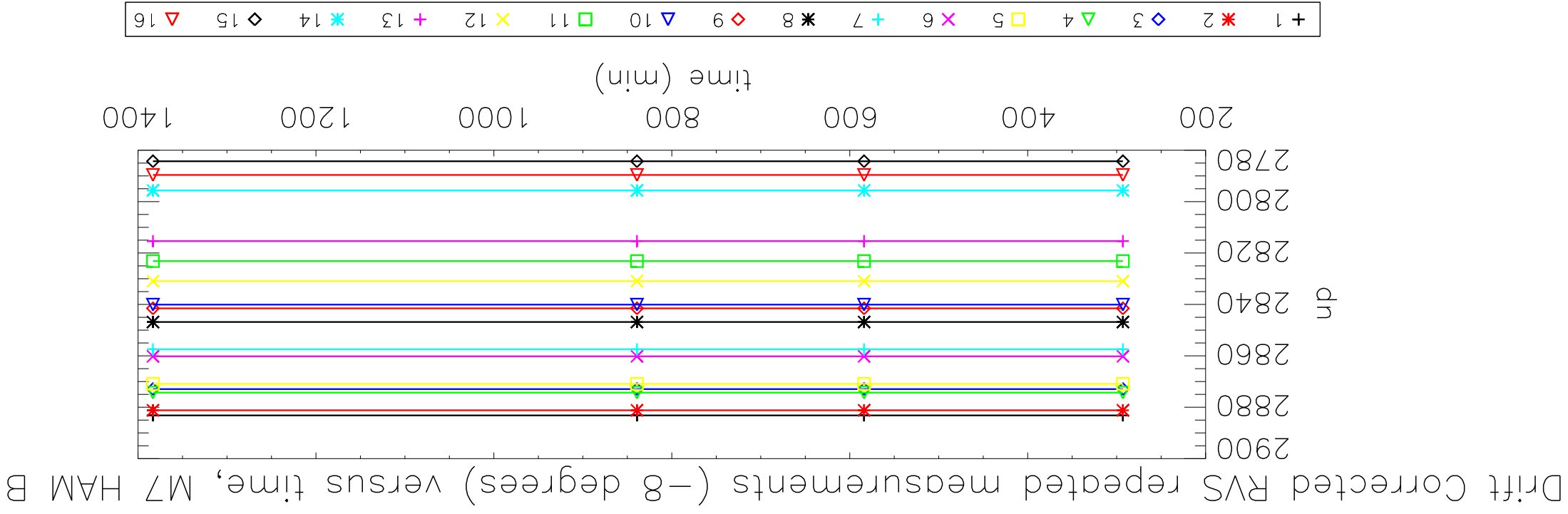
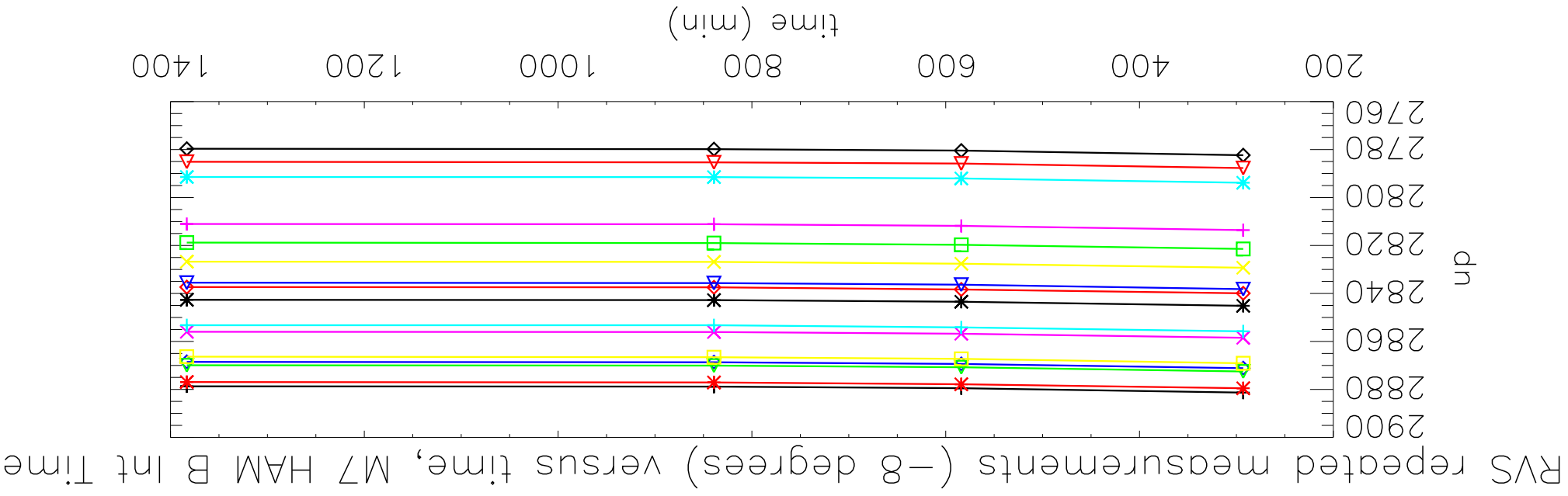


RVS repeated measurements (–8 degrees) versus time, M7 HAM A Int Time

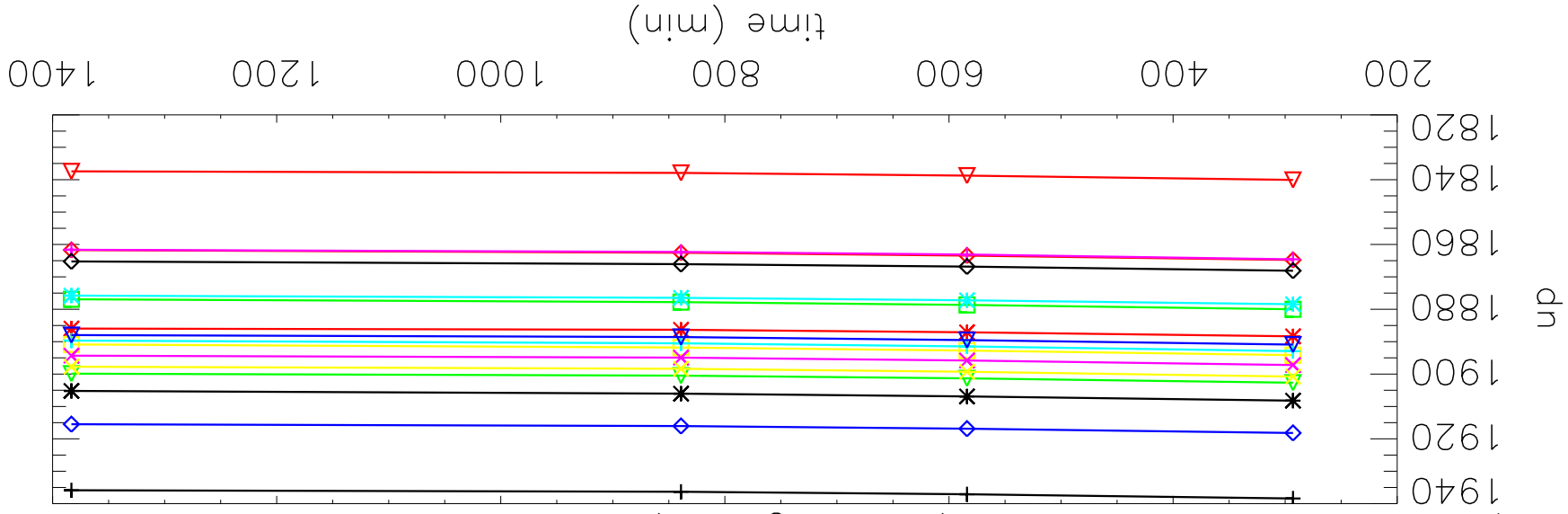


Drift Corrected RVS repeated measurements (–8 degrees) versus time, M7 HAM A Int Time

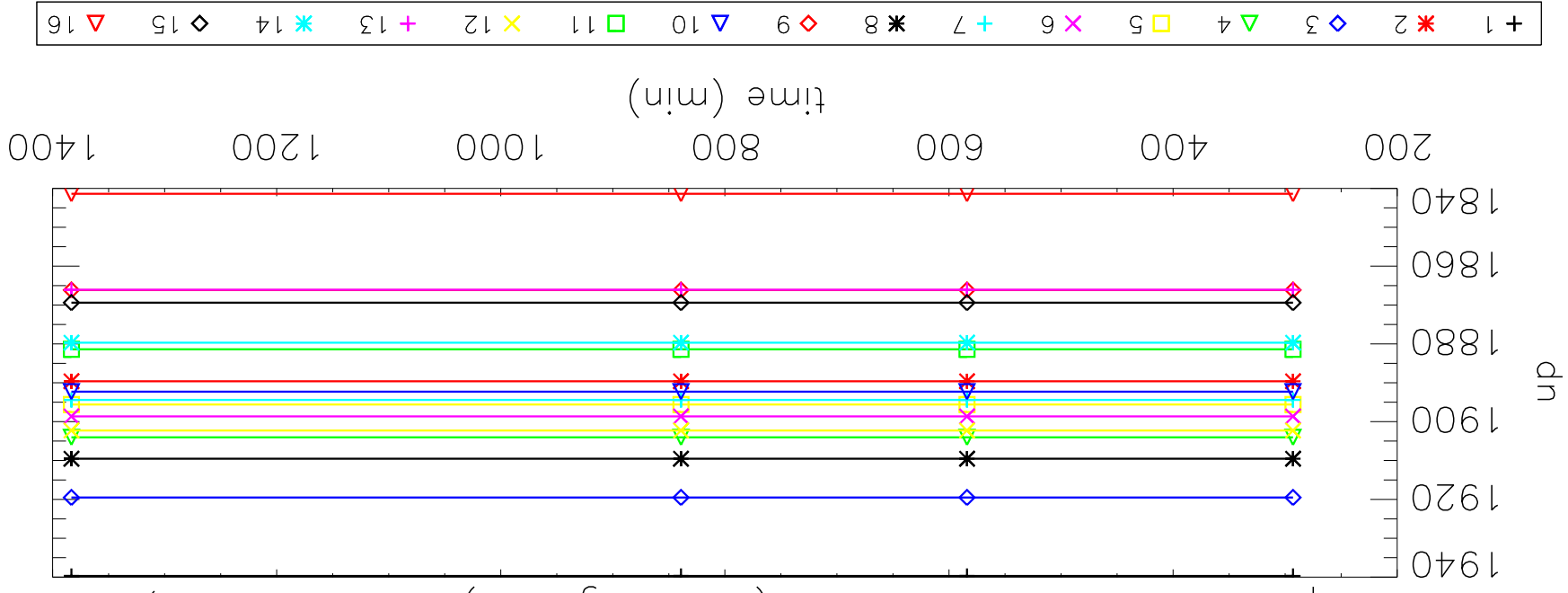


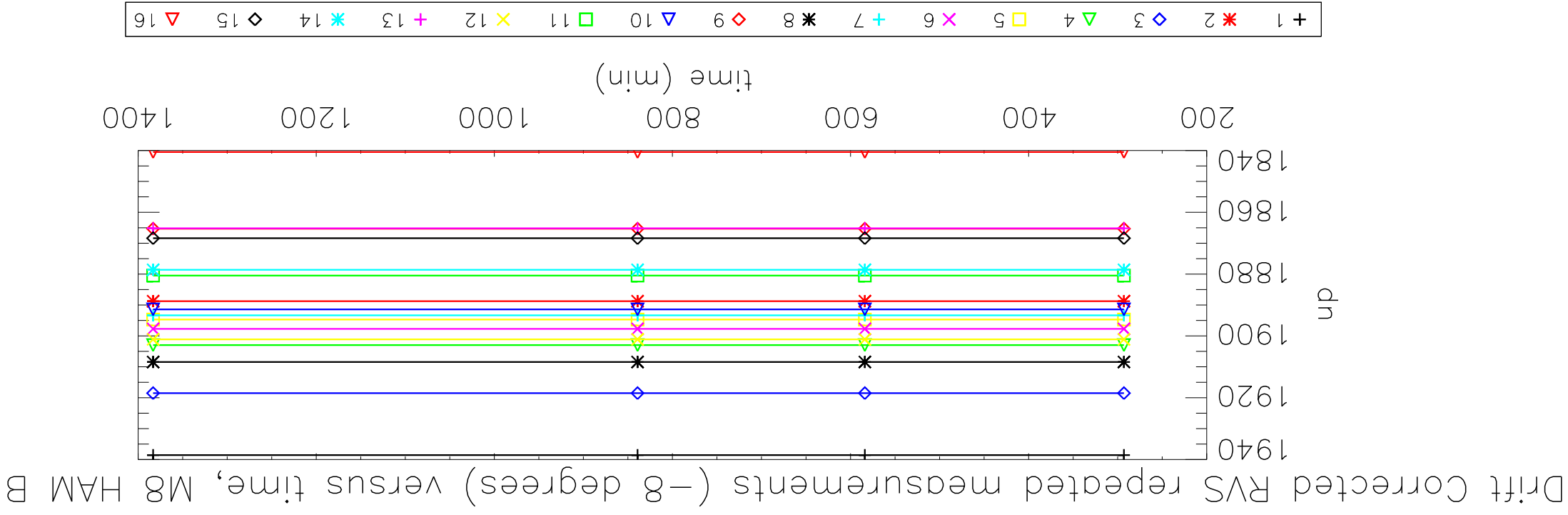
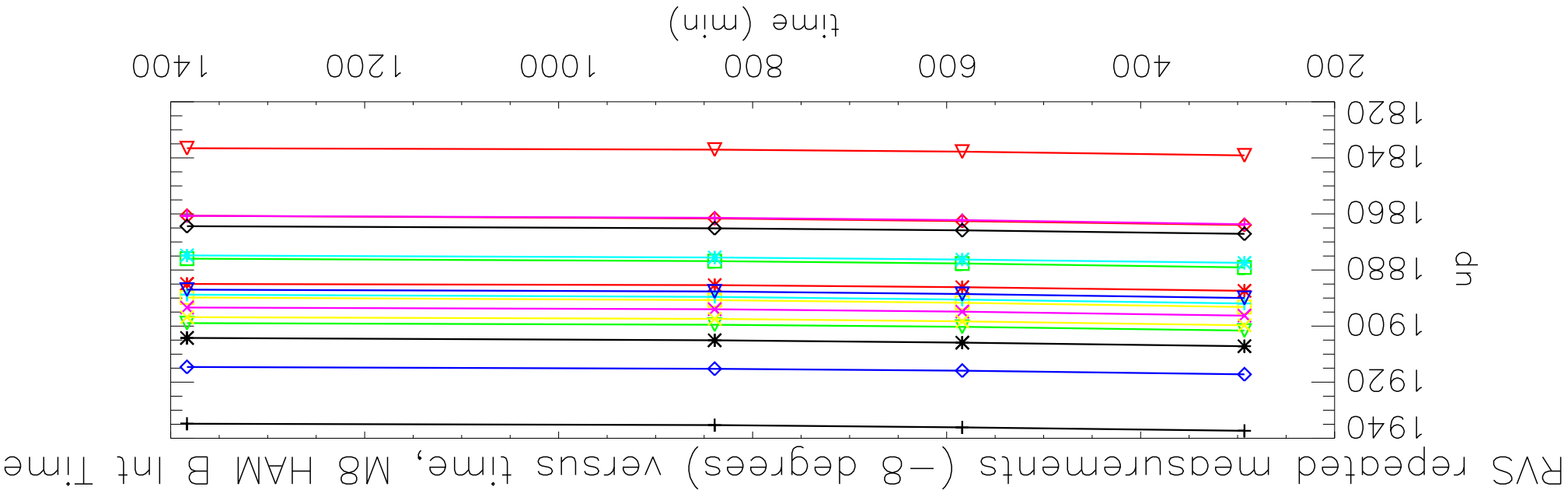


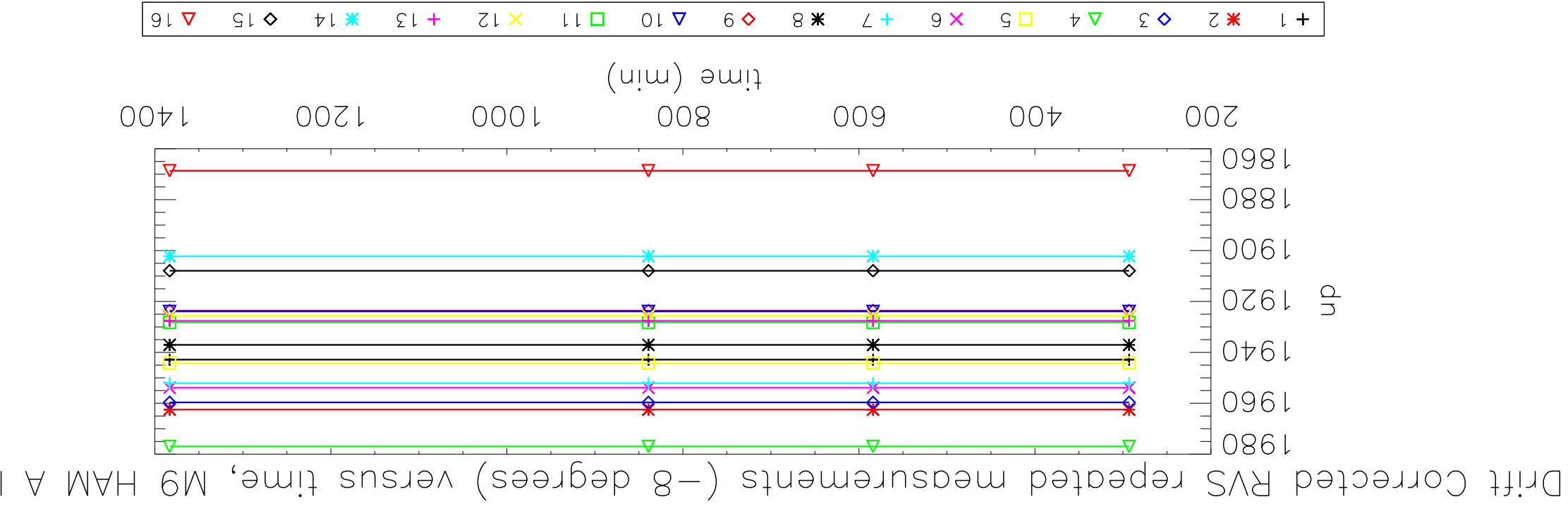
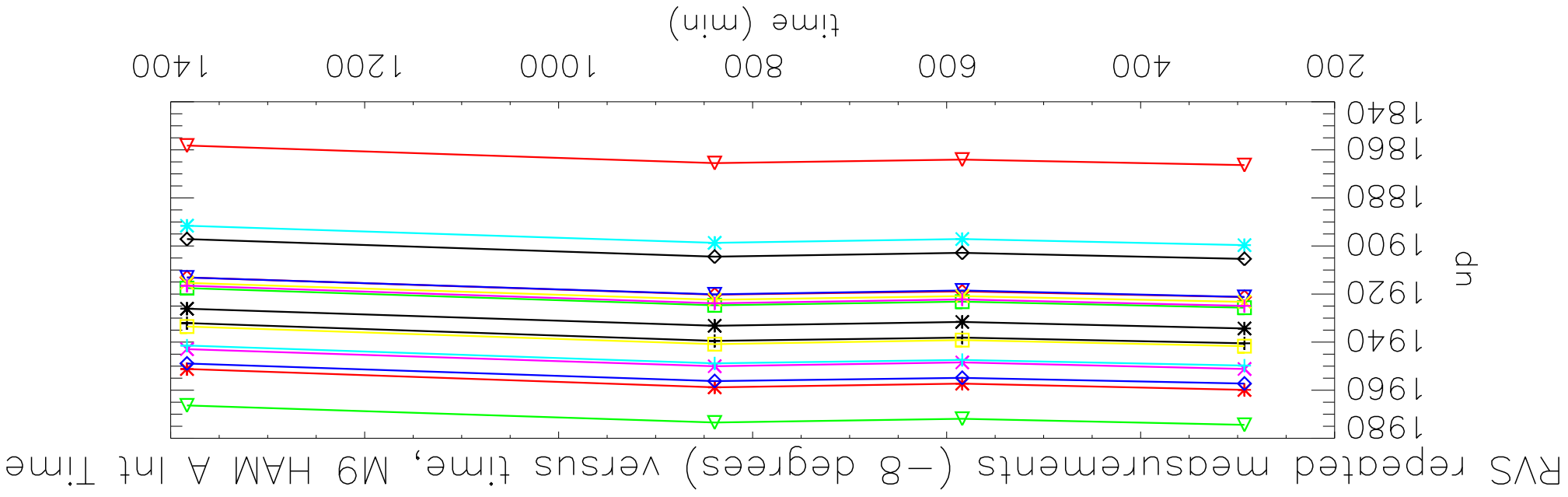
RVS repeated measurements (–8 degrees) versus time, M8 HAM A Int Time

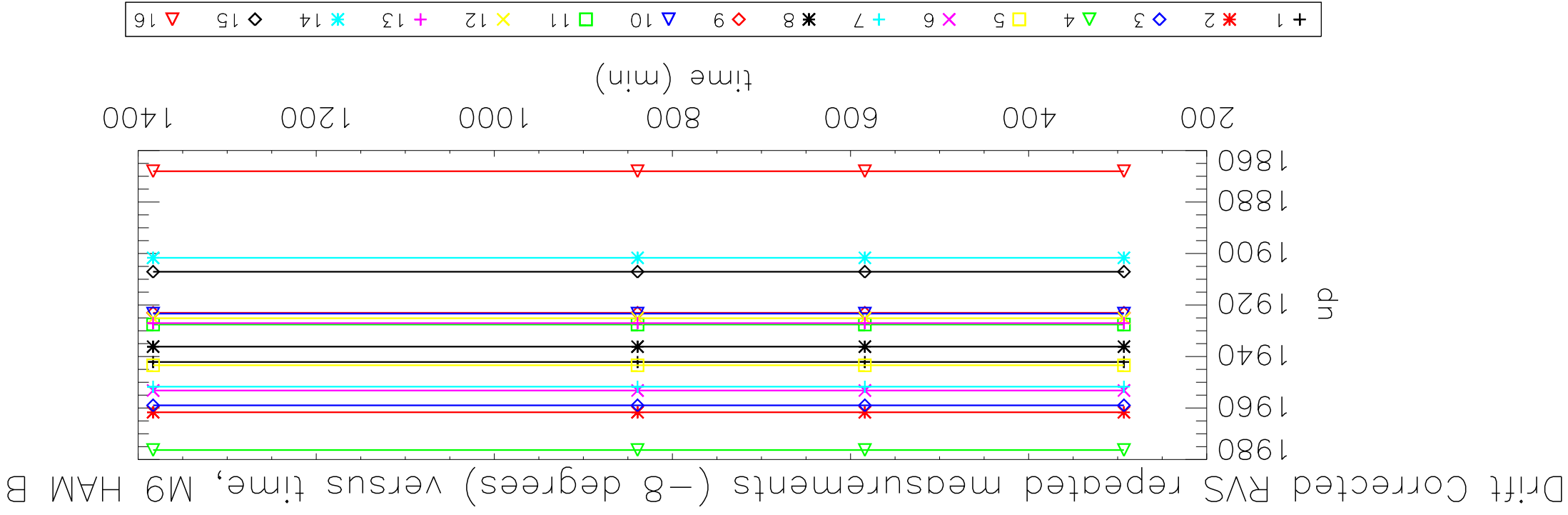
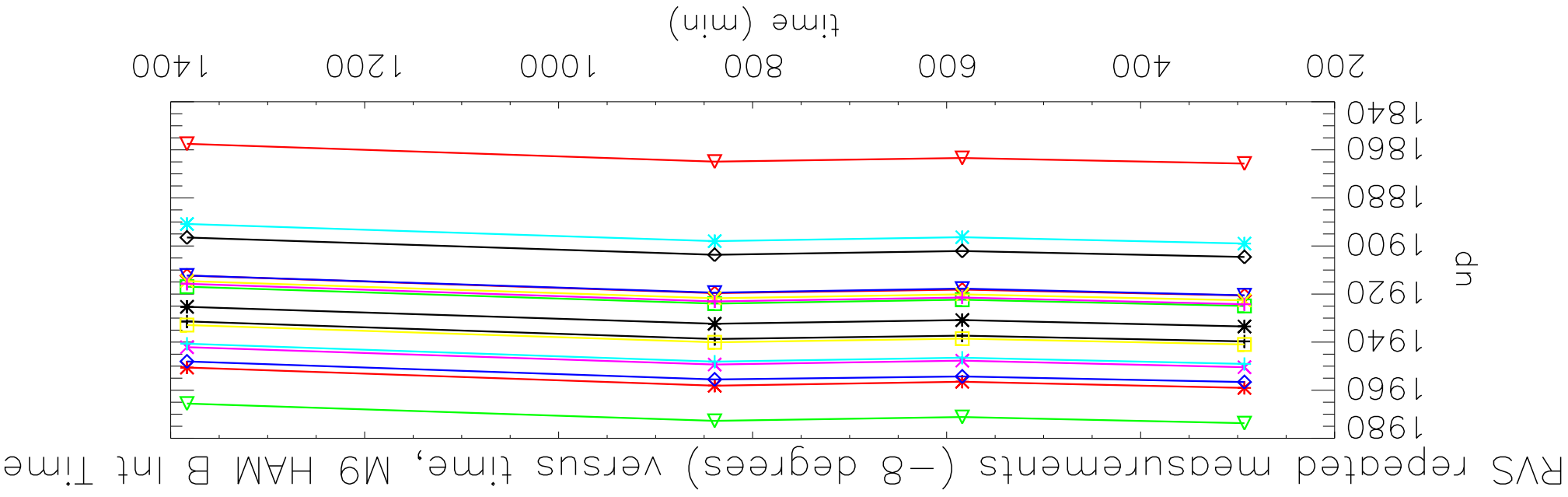


Drift Corrected RVS repeated measurements (–8 degrees) versus time, M8 HAM A Int Time

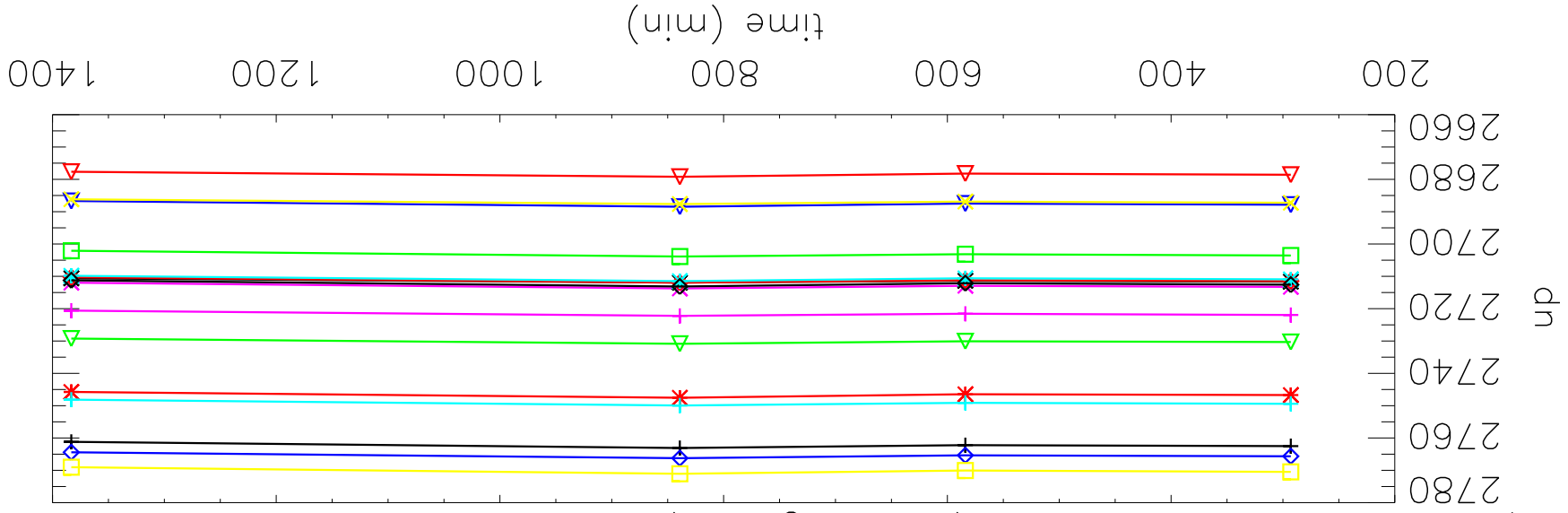




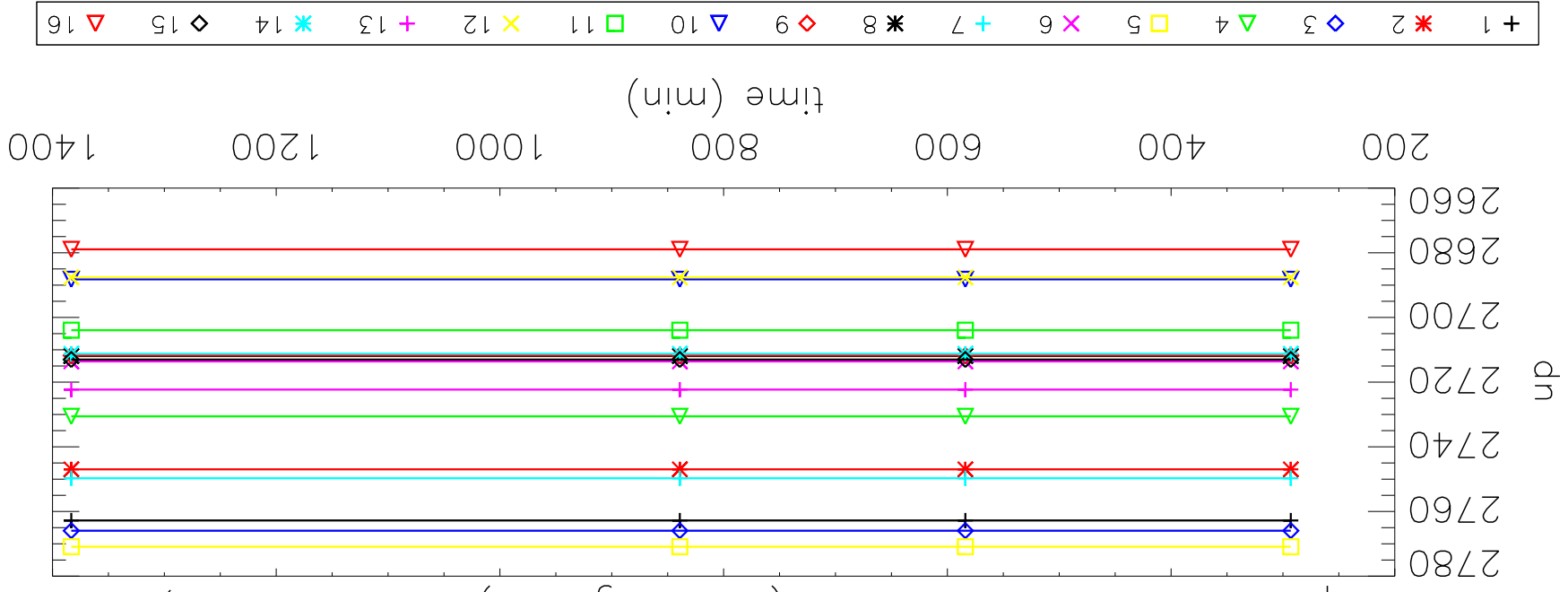




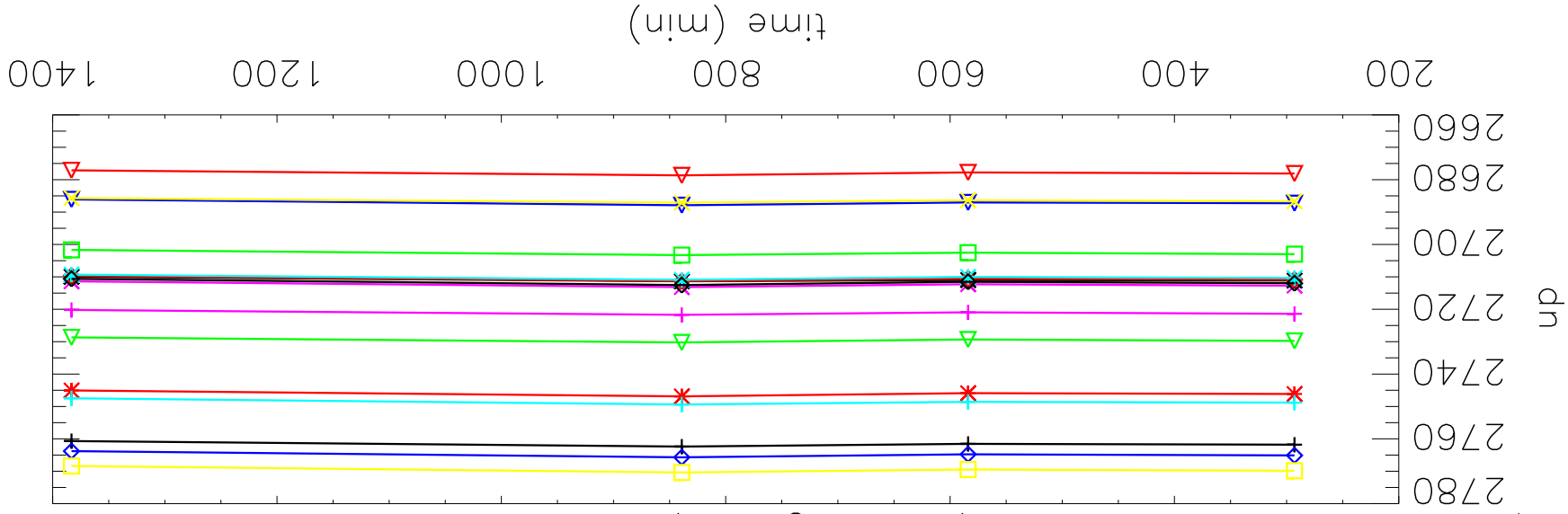
RVS repeated measurements (–8 degrees) versus time, M10 HAM A Int-Time



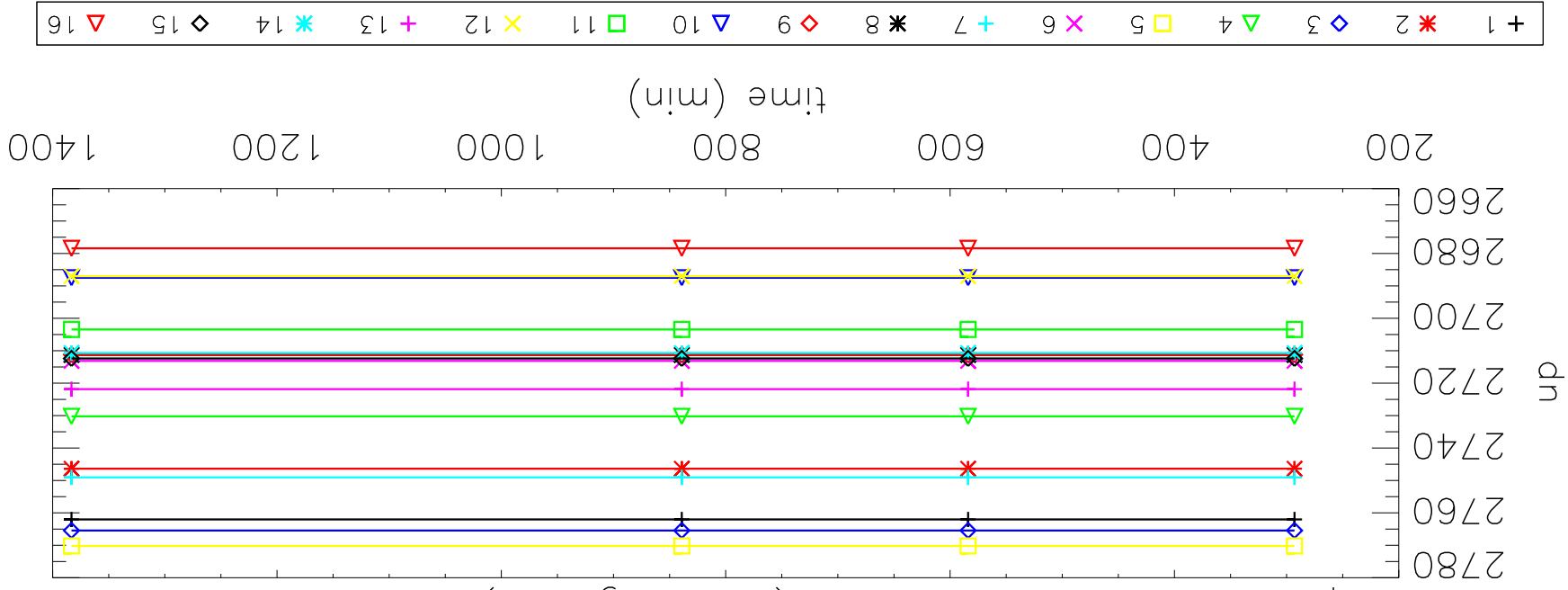
Drift Corrected RVS repeated measurements (–8 degrees) versus time, M10 HAM A



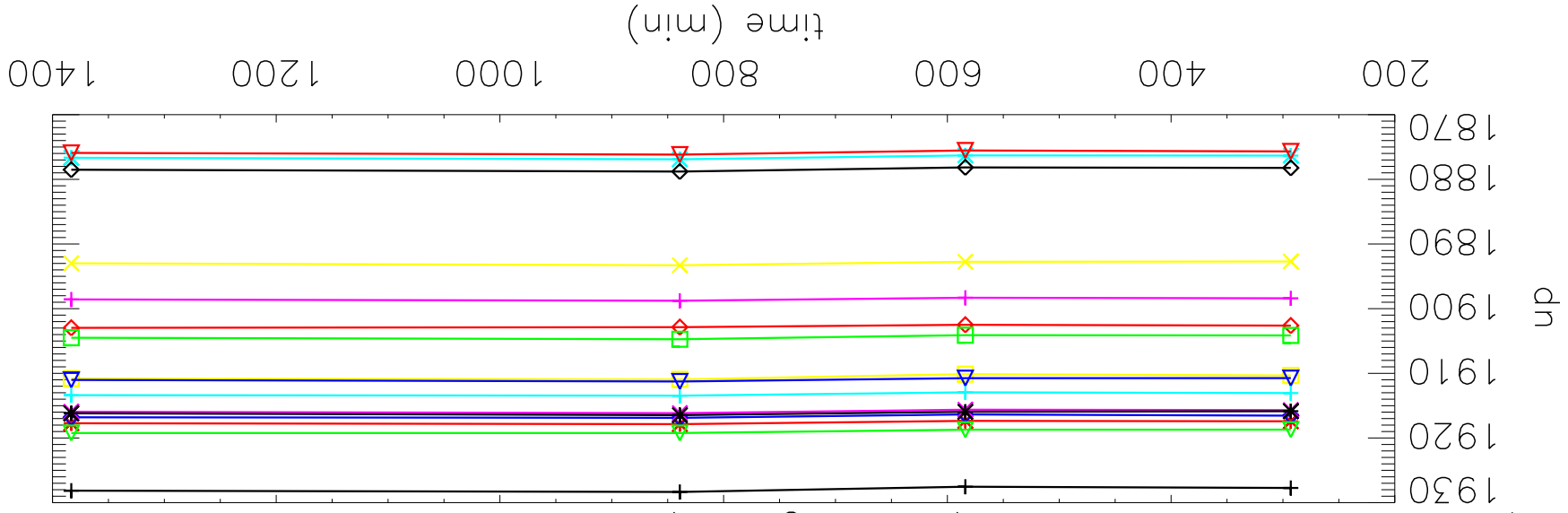
RVS repeated measurements (–8 degrees) versus time, M10 HAM B Int-Time



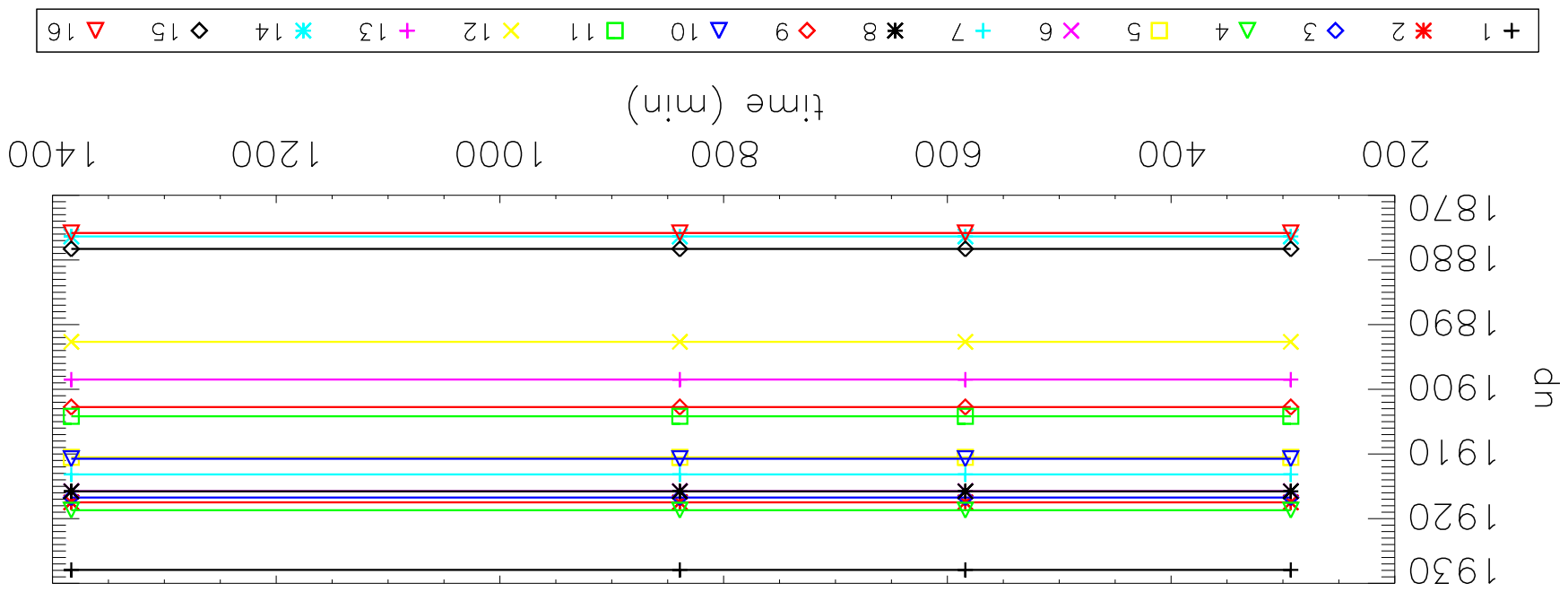
Drift Corrected RVS repeated measurements (–8 degrees) versus time, M10 HAM B



RVS repeated measurements (–8 degrees) versus time, M11 HAM A Int-Time

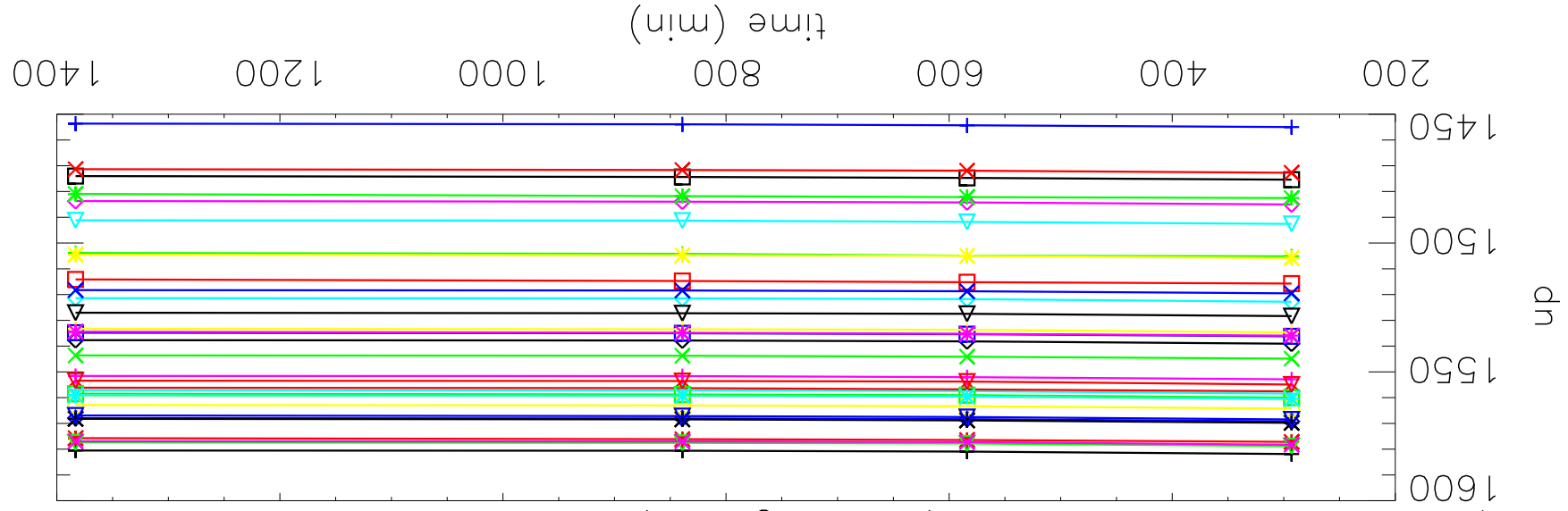


Drift Corrected RVS repeated measurements (–8 degrees) versus time, M11 HAM A

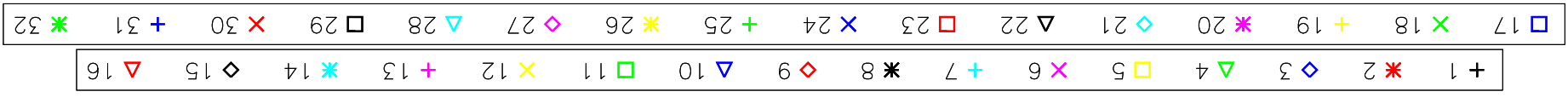
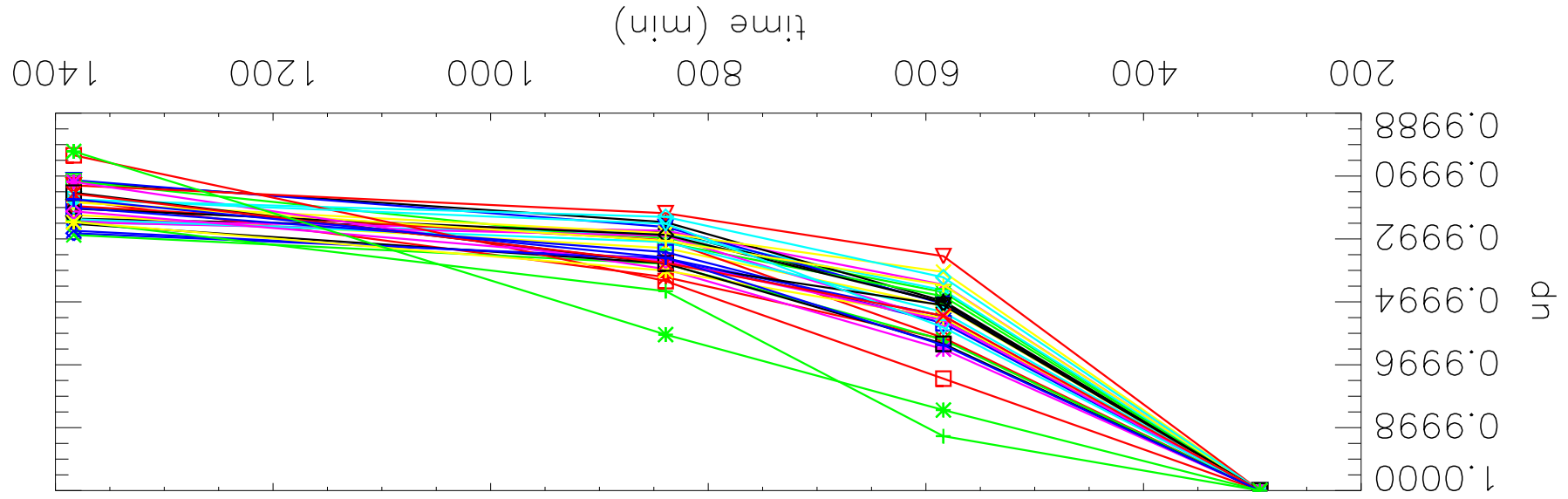


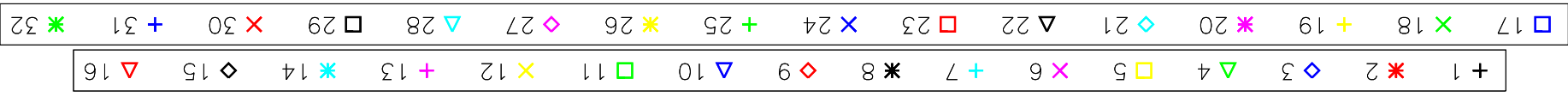
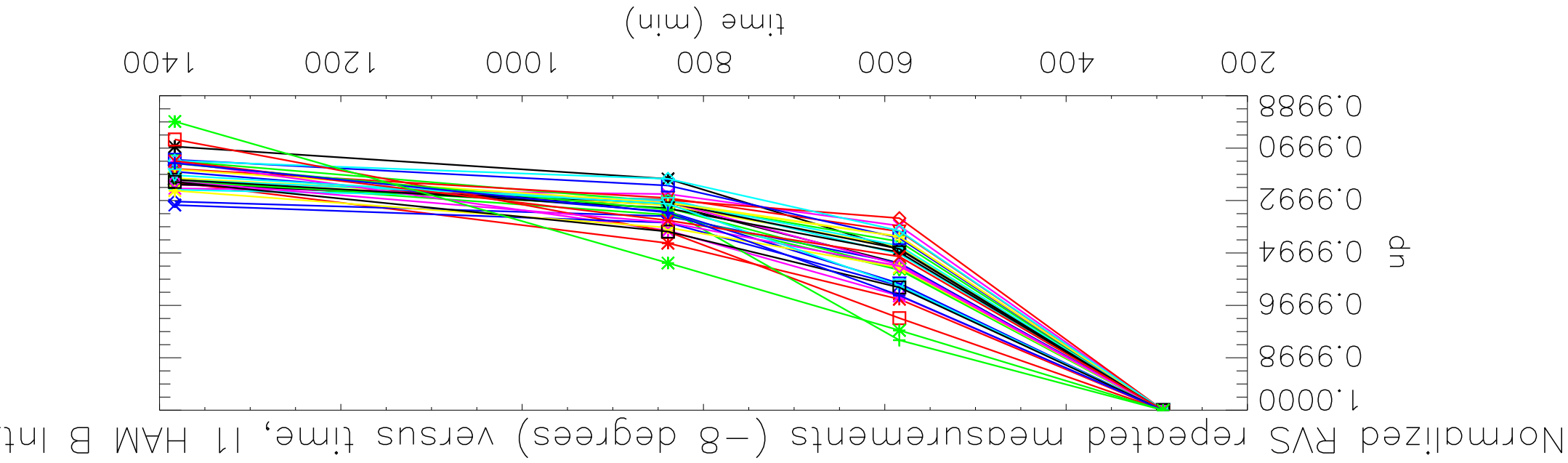
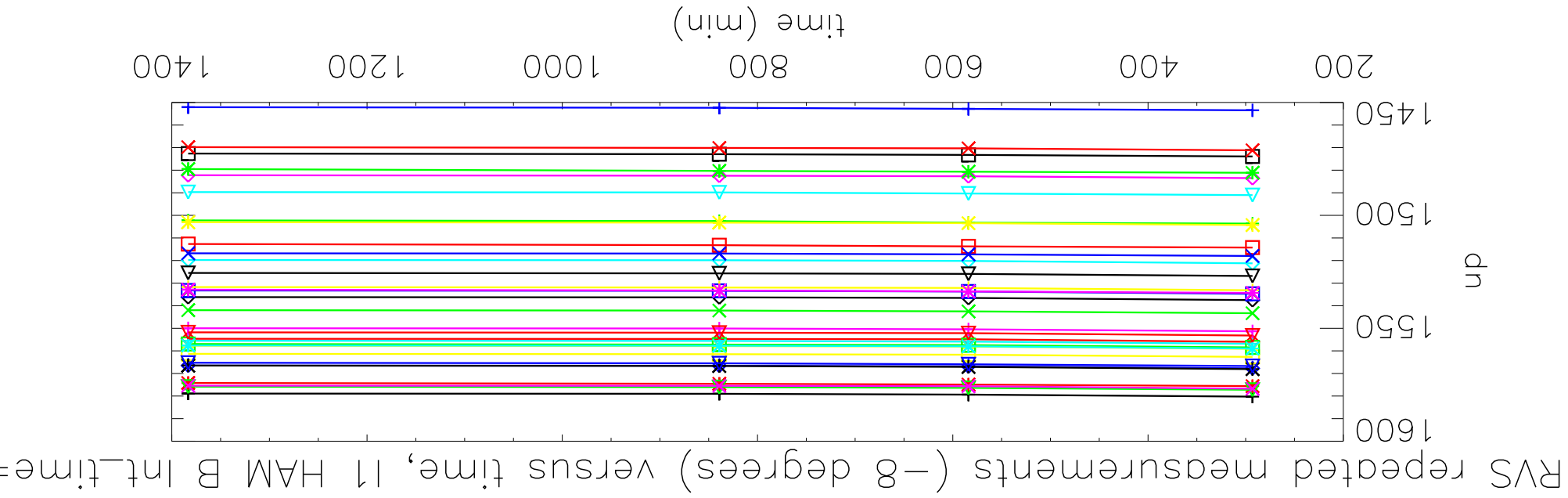


RVS repeated measurements (−8 degrees) versus time, 11 HAM A Int-time=

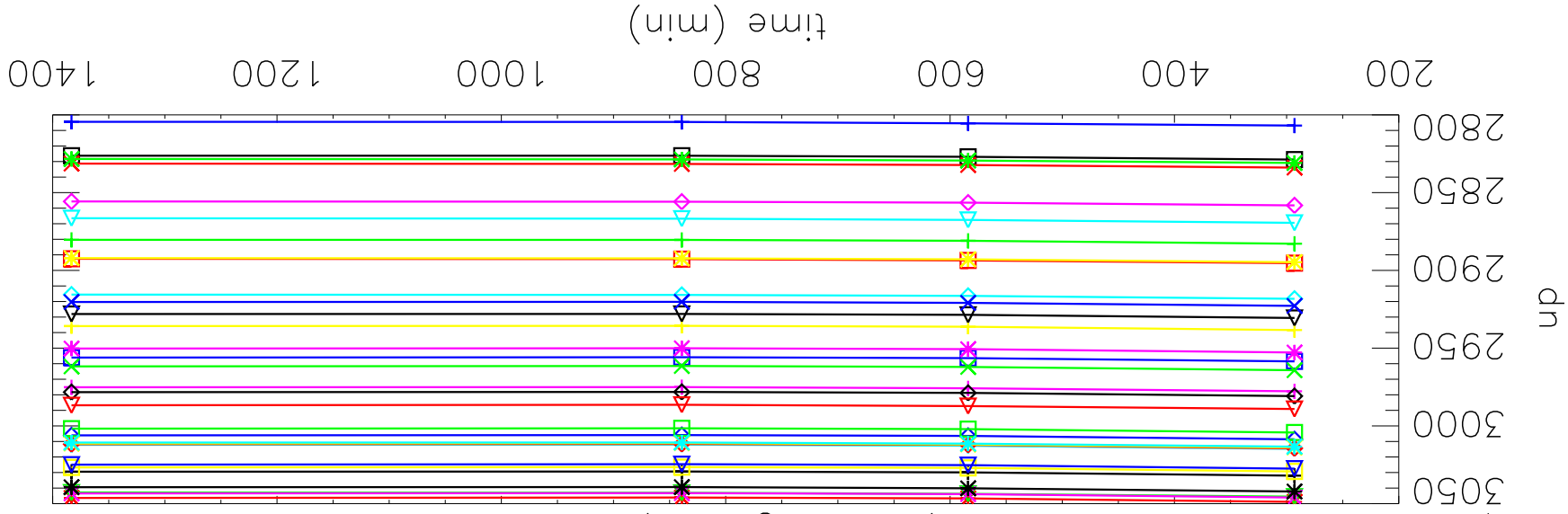


Normalized RVS repeated measurements (−8 degrees) versus time, 11 HAM A Int-

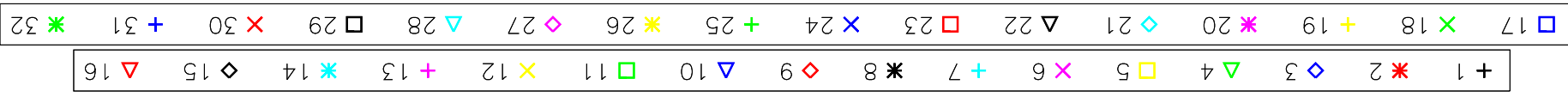
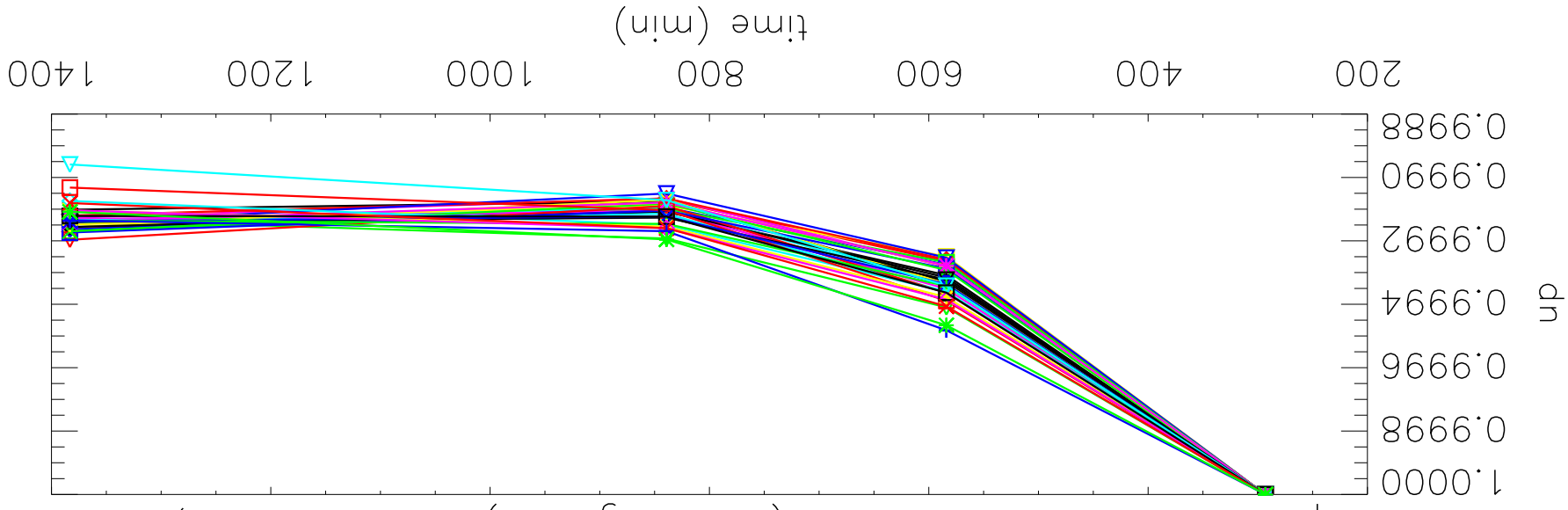


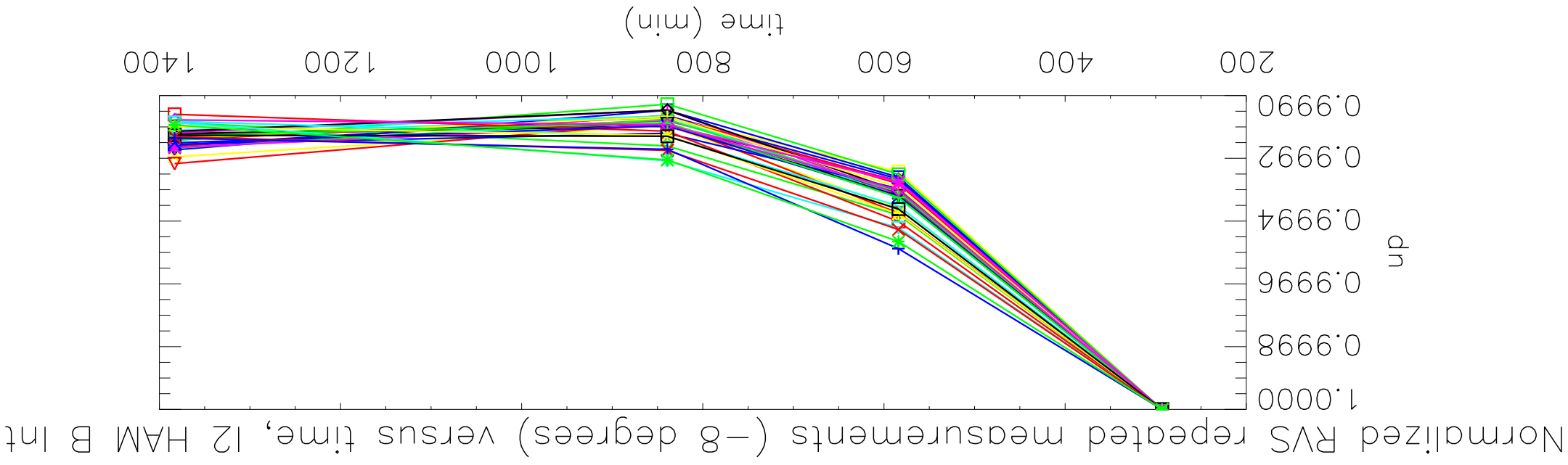
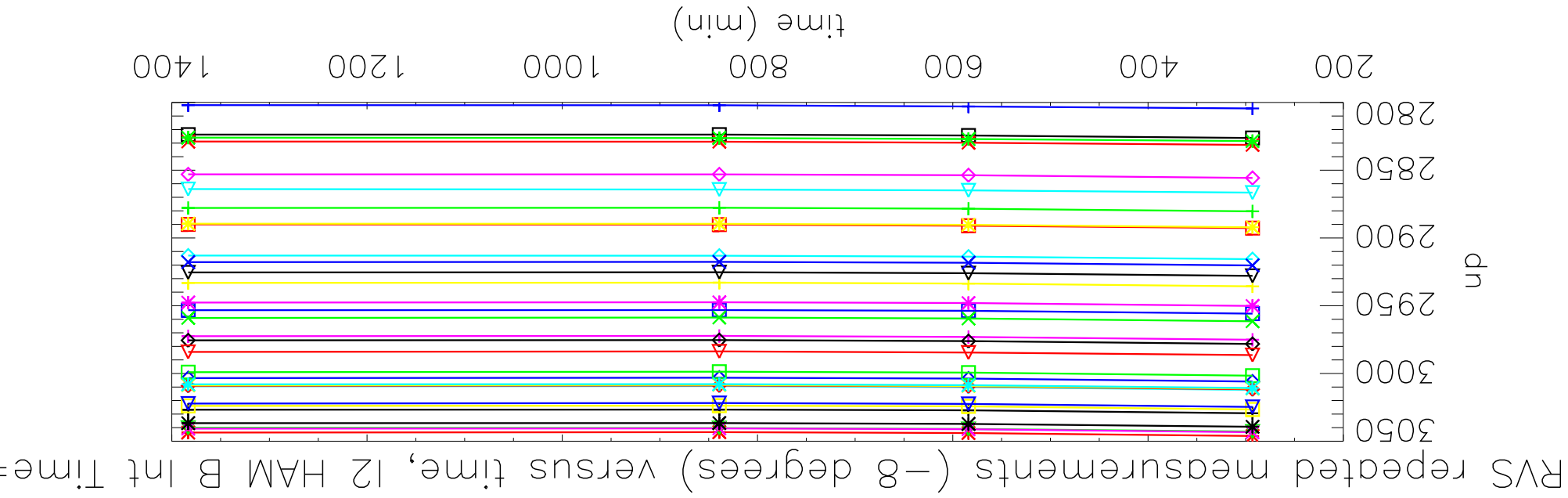


RVS repeated measurements (–8 degrees) versus time, 12 HAM A Int

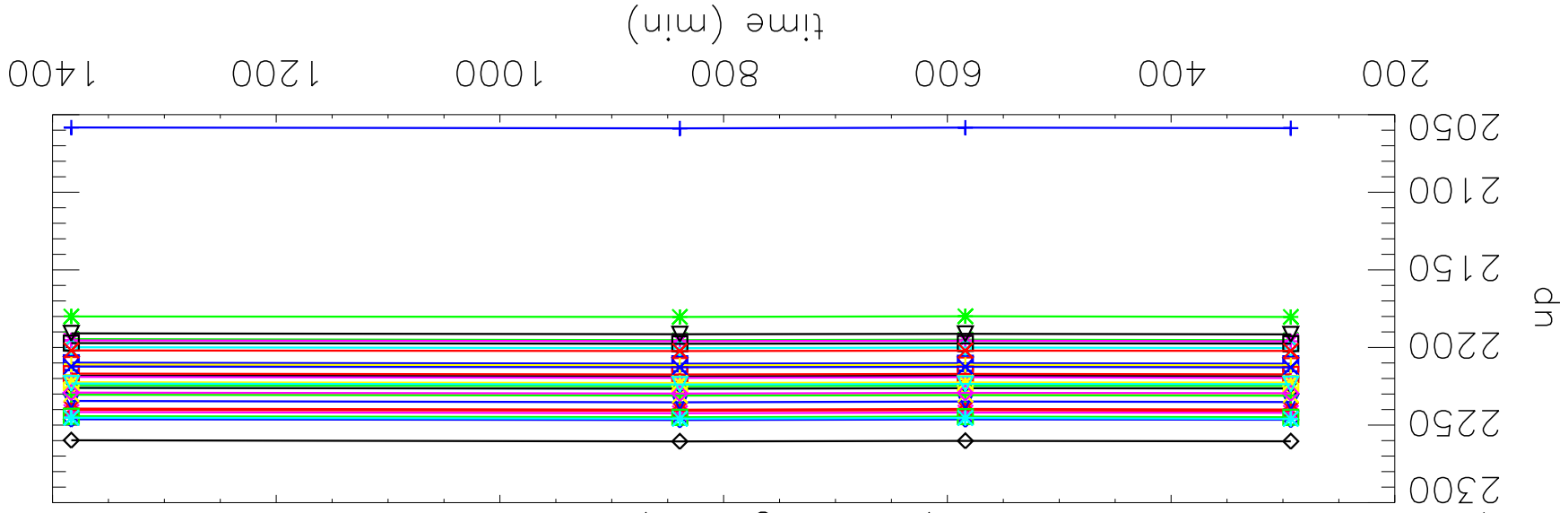


Normalized RVS repeated measurements (–8 degrees) versus time, 12 HAM A Int





RVS repeated measurements (−8 degrees) versus time, 13 HAM A Int Time=



Normalized RVS repeated measurements (−8 degrees) versus time, 13 HAM A Int

