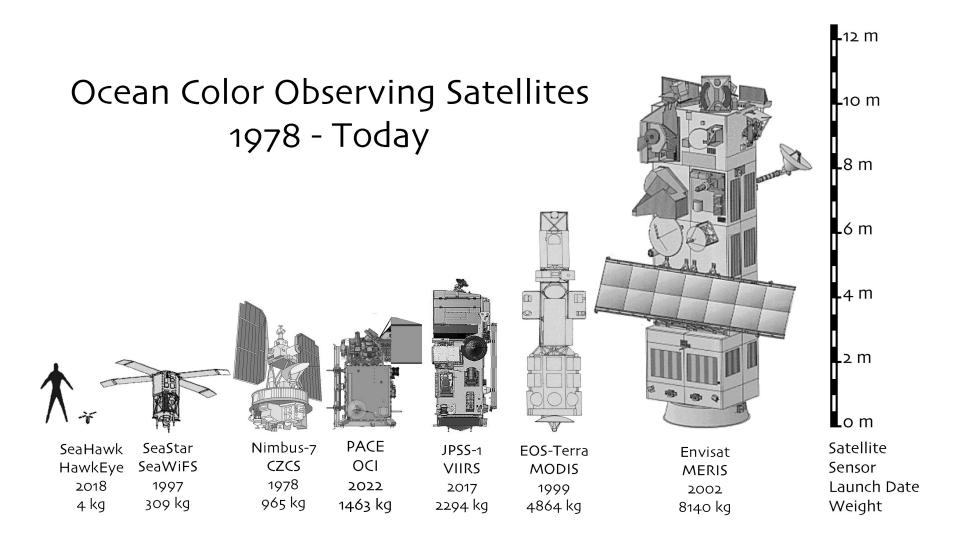
SeaHawk - HawkEye

Background, Overview and Status 28 May 2020

SOCON

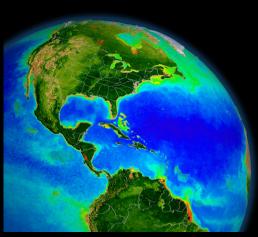
Sustained Ocean Color Observation from Nanosatellites

CHARLES WEST



Goal:

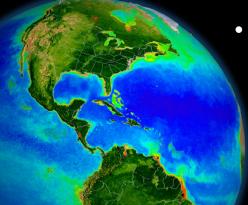
Proof of Concept program to demonstrate whether it is possible to obtain high quality, high resolution (~100m) ocean color imagery using a low-cost miniature ocean color sensor carried aboard a CubeSat.



- Program was funded (2015) by the Gordon and Betty Moore Foundation - *Phase 1:* Design and Construction of SeaHawk Satellite Bus and HawkEye Ocean Color Sensor
 - Clyde Space (Scotland) provides the CubeSat bus named
 SeaHawk-1 and SeaHawk-2
 - Alan Holmes and his team at Cloudland Instruments (Calif) provides the Hawkeye Sensors
- The program is administered by Dr. John Morrison UNCW

https://uncw.edu/socon/

• NASA provided "advice and review" during the development phase and with formal NASA/HQ Space Act Agreement (2017), provides support for the collection, processing, calibration, validation, archive and distribution of the data (see backup for details)



A second Moore Foundation grant was awarded in June 2017 for *Phase 2* to support the commercial launch and operations of both spacecraft and instruments for duration of 2 years each.

Key Mission Parameters

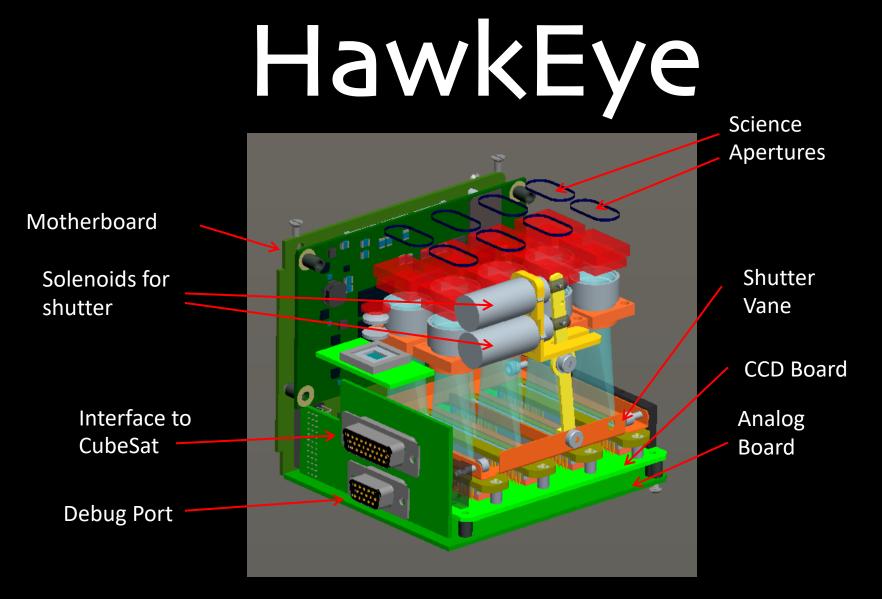
- 1. Launched 3 December 2018 (3 weeks before government shutdown)
- 2. Nominal orbital height = 585 km (- 1 km today)
- 3. Sun-synchronous around 10:30am
- 4. 18 day repeat orbit (one satellite)
- 5. Baseline orbital lifetime of 1 year (18-24 month)
- Image size of 200 x 600km of approximately 120 meter resolution - 100MB/scene)
- X-band downlink (Wallops & Alaska) data rate of 6 --> 100mbs

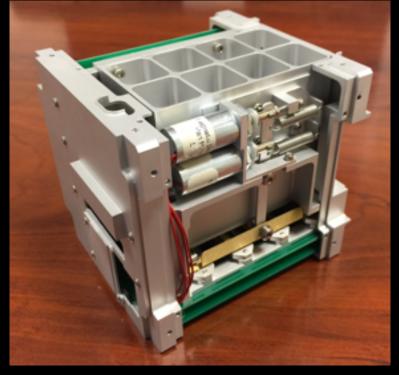
Nadir

Flight

Direction

- Weight of instrument less than 1 kilogram
- Total weight of spacecraft plus instrument less than 5 kilograms
- Off-the-shelf CCD arrays used
- Sensitivity comparable to SeaWiFS
- 8 SeaWiFS Bands (see backup)
- Open intellectual property and knowledge sharing









SeaHawk Internal Configuration

Power Subsystem:

Clyde Space 3G EPS Motherboard with a Flex daughterboard

3G 30 Whr Clyde Space battery

Solar Arrays

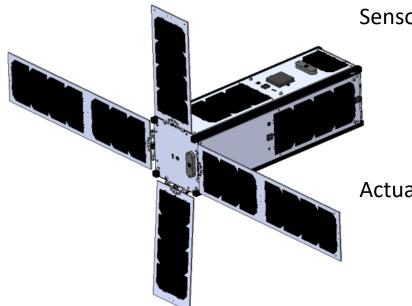
Communications Subsystem:

VHF uplink at 1200 bps and UHF downlink at 9600 bps Syrlinks X-band Transmitter (3-50Mbps / 6-100Msps)

On Board Computer:

Clyde Space on-board computer (OBC) provide up to 1.8 GB payload data storage **Attitude Determination & Control:**

Clyde Space ADCS Motherboard

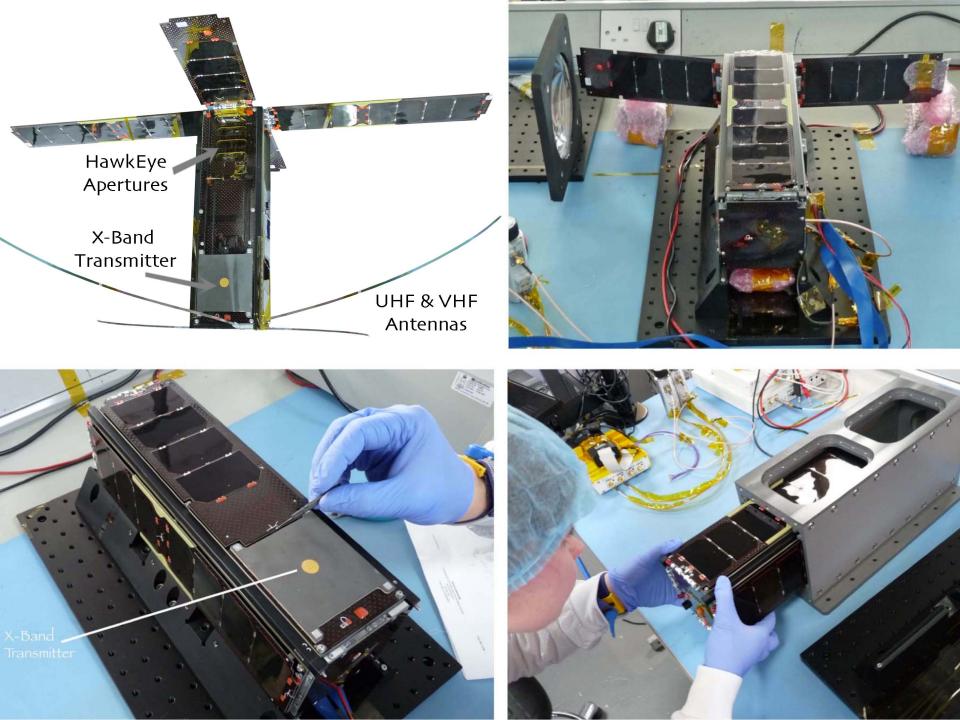


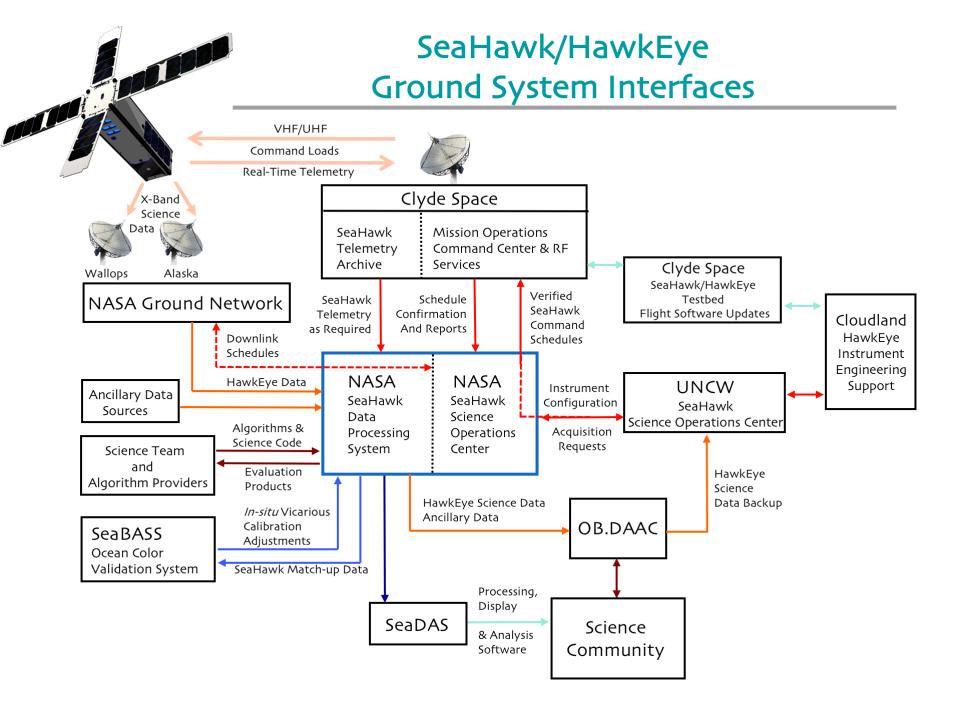
Sensors:

Course sun sensors Three 2 Axis Digital Fine Sun Sensors Magnetometers Rate Gyroscopes GPS

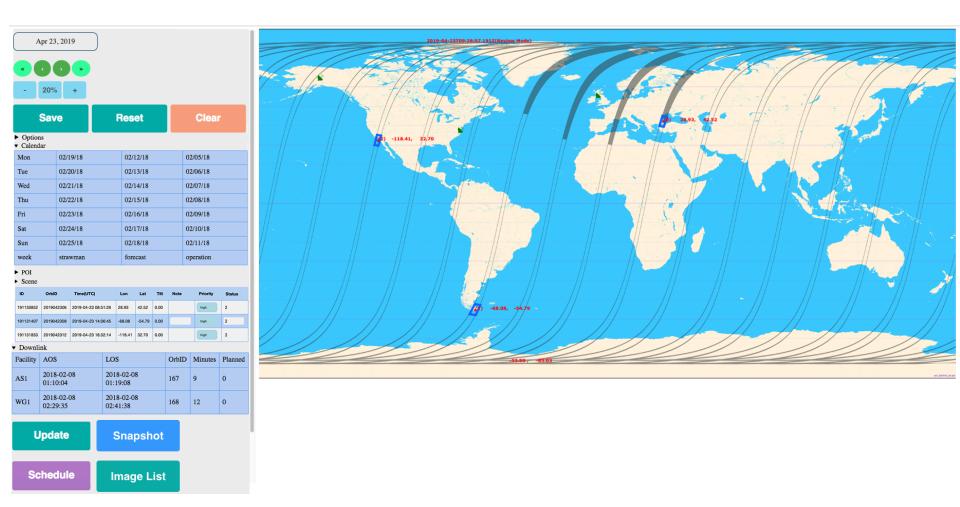
Actuators:

Three Axis Reaction Wheels Three Axis Magnetorquers (MTQ)

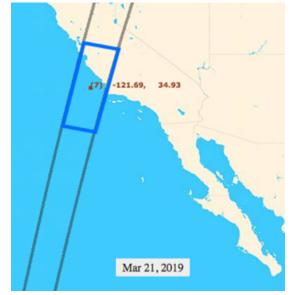




HawkEye Instrument & SeaHawk X-band Downlink Scheduling Tool

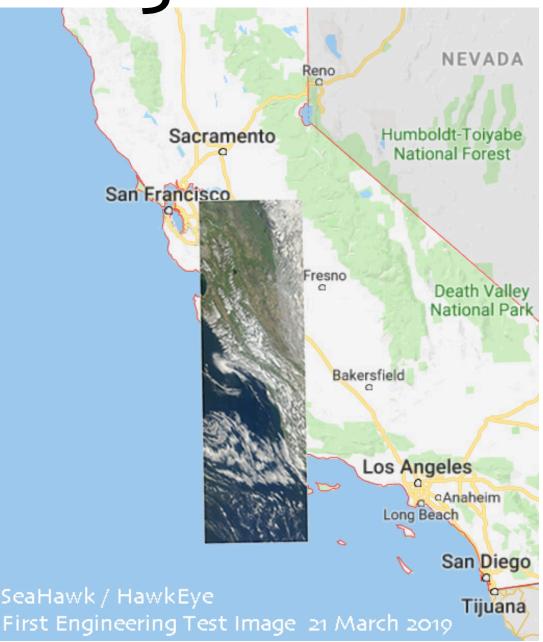


First Light



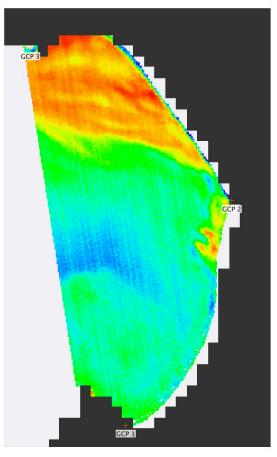
Sequence of Events:

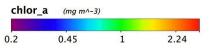
- 20 March: x-panels deployed HawkEye optics exposed
- 21 March: 1st image acquired
- 22 March: Wallops X-band downlink 50 mbps

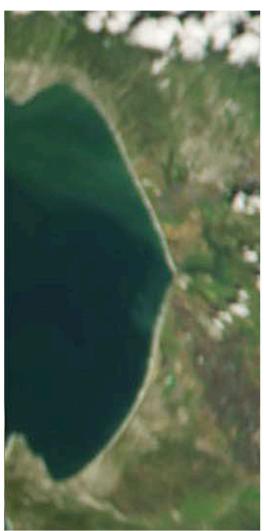


Chlorophyll-a Concentration

HawkEye / SeaHawk 21 March 2019

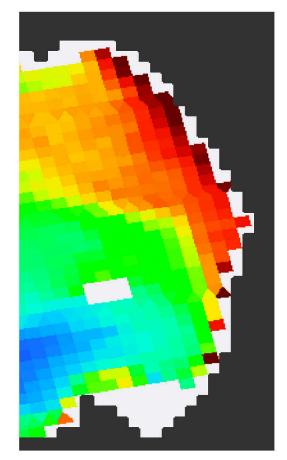






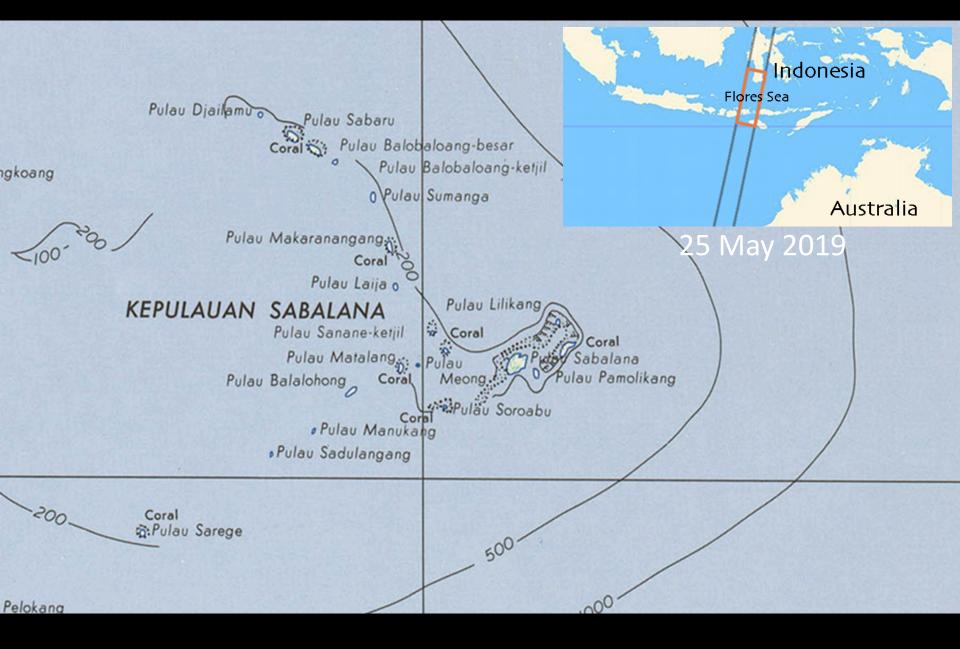
HawkEye True Color Monterey Bay

MODIS / Aqua 20 March 2019

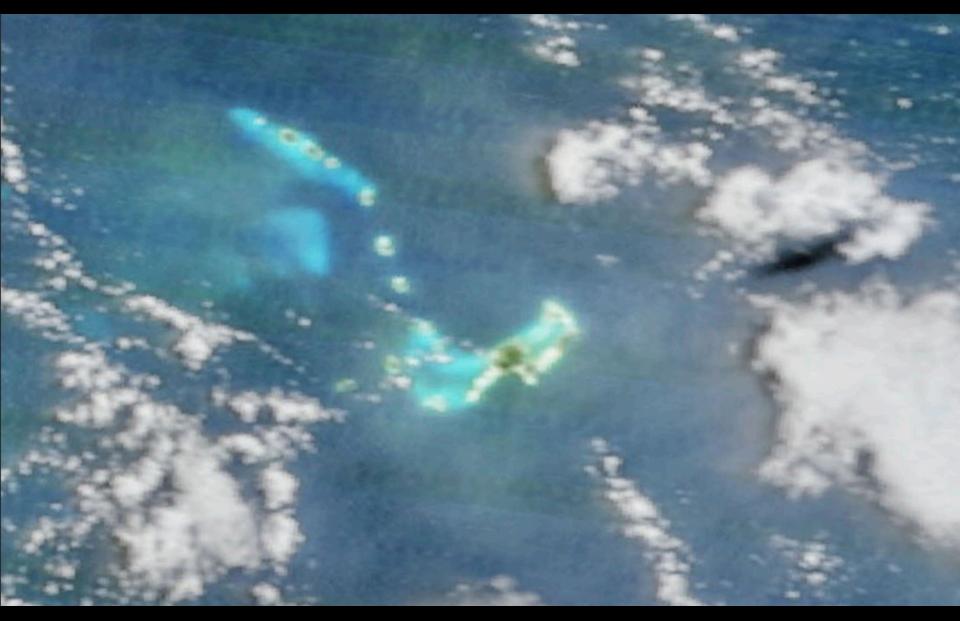


chlor_a	(mg m^-3)		
0.1	0.38	1.41	5.32

Proof of Concept CONFIRMED



MODIS / Terra 25 May 2019 True Color



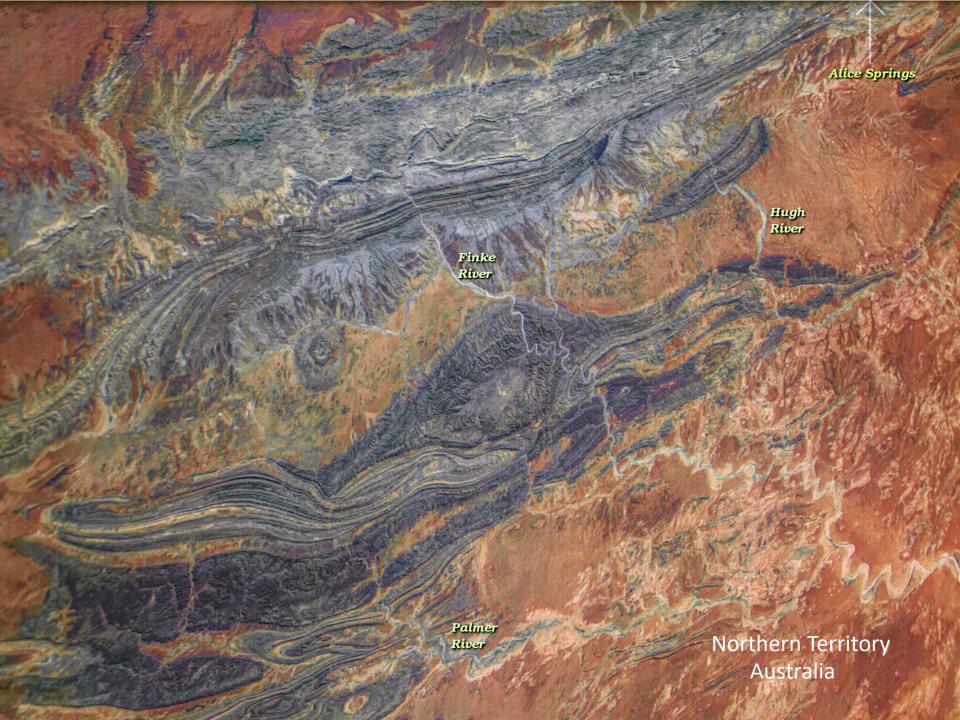
HawkEye / SeaHawk 25 May 2019 True Color



Adelaide, Australia

Long Island, New York

Gulf of Carpentaria



Exmouth Western Australia

Western Greece

Chatham Rise New Zealand

Current Status

- 1. Nearly 18 months of on-orbit operations
- 2. 135 HawkEye images collected, downlinked and processed to Level-1a
- 3. 27 successful x-Band data downlinks at NASA/Wallops (100mbps)
- 4. Automated data processing in place from downlink to Level-2
- 5. HawkEye instrument has shown no signs of on-orbit degradation
- 6. SeaHawk spacecraft has only lost 1 km of orbital altitude since launch.
- 7. No end of mission trends observed in spacecraft systems
- 8. As yet unresolved spacecraft stability issue believed related to the coupling between the onboard attitude sensors and the control system.

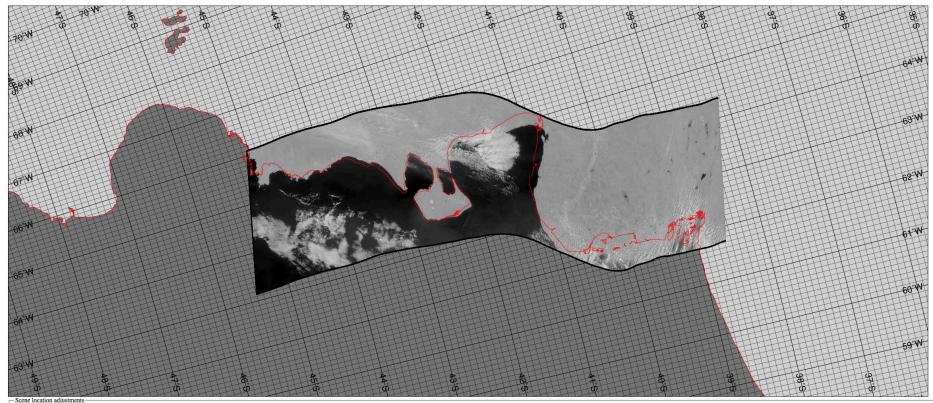


Renavigation tool to geolocate imagery

/web/oceancolor/HawkEye/HWK2020040140634.L2_RENAV.nc

0 (0%) out of 6 scenes disposed of.

Drag the scene to align it with the map. Please wait a few moments for the scene to paint on the map. If the map does not appear at all, then please select "Bad data". This Google Maps link may help you determine what part of the world you are looking at.



Along track: 31.434 kilometers Cross track: -8.513 kilometers Skip Bad data Water only Land only Cannot discern coastline No fix by translation alone Submit Adjustments

computed pixel resolution: 131 meters

NEXT STEPS

- 1. Identify and Verify Attitude Control root cause and implement required fix
- 2. Define revised Nominal Operations concept for SeaHawk-1
- 3. Verify and transition to *Nominal Operations* phase of mission
- 4. Begin soliciting image requests from the Community (see backup)
- 5. Release processing software in SeaDAS and data via OB.DAAC
- 6. Assemble all "Lessons Learned" from SeaHawk-1
 - 1. Hardware 2. Software 3. Concept of Operations 4. Testing
- 7. Develop workplan and schedule for SeaHawk-2 and path forward

Finderscope Image 26 April 2016

BACKUP

INSTRUMENT DETAILS

The HawkEye Instrument is designed to capture an image of the oceans and earth with 120 meter per pixel resolution from a 575 km nominal orbit. Each image will have dimensions of 1800x 6000 pixels, 8 bands deep. The bands are similar to those used by the **SeaWiFS instrument**. The instrument is of push-broom design, with 4 linear array CCDs, each containing 3 rows of detectors, scanning the field of view as the satellite passes overhead. The instrument is designed to not saturate on either the land or clouds using a technique called bi-linear gain. The ground swath imaged will be approximately 216 x 720 km in extent (134 x 448 miles).

Band	Wavelength	Bandwidth
	in nm	in nm
SeaWiFS 1	412	20
SeaWiFS 2	443	20
SeaWiFS 3	490	20
SeaWiFS 4	510	20
SeaWiFS 5	555	20
SeaWiFS 6	670	20
New 7	750.9	14.7
SeaWiFS 8	865	40

Optical Design and Radiometric Considerations...

Lessons from Prototype Testing...

CCD University – How to implement a CCD...

Mechanical Design...

Electronics Design...

Software Implementation...

Presentations available at: http://cloudlandinstruments.com/?page_id=188

NONREIMBURSABLE SPACE ACT AGREEMENT BETWEEN NASA/SMD and UNIVERSITY OF NORTH CAROLINA AT WILMINGTON EFFECTIVE DATE 6/1/2017 EXPIRATION DATE 6/1/2022

NASA Responsibilities:

Mission Planning & Integration and NEN

Coverage and loading analyses Networks Documentation and Reviews RF Compatibility Testing and Reports On-Orbit Services NEN Aperture Fees are based upon 4 passes per day NEN Mission Configuration and Test Services

Ocean Biology Processing Group

Prelaunch advisors to the HawkEye instrument and SeaHawk cubesat Develop Level o-to-2 processing software Pre-launch characterization of the Hawkeye with Cloudland Instruments Instrument scheduling procedures with Clyde Space Downlink scheduling with NASA/NEN Data processing of the SeaHawk Archive and distribution of SeaHawk data to the research community Code 618 Calibration Facility

Use of NASA Portable integrating sphere for pre-launch calibration

135 Targets imaged by HawkEye

Monterey Bay
North Carolina
Coast
India (Mumbai)
Cape Horn
Cape Horn Long Island
Tasmania
San Francisco
Gulf of Suez
Puerto Rico
Baja California
Flores Sea Rio de la Plata
Southern CA
Gulf of Mexico
Lake Maracaibo
Cuba and Jamaica
New York Bight
Mid-Atlantic
South Atlantic Bight
Scotland
MOBY
Scotland
Lake Titicaca
Scotland
Scotland
Scotland
Lake Michagan
Samoa
West Coast
Australia
Buenos Aires
Nova Scotia
India, Gulf of
Khambhat
Catalina Islands
Yangtse River
Crete
Crete Gulf of Maine
Gulf of Maine
Gulf of Maine Eastern Long Island
Gulf of Maine Eastern Long Island MOBY
Gulf of Maine Eastern Long Island

Ireland Northern
Scotland
Lake Atitlan
Guatamala
San Franciso and
Monterey Bay
Outer banks
Chesapeake
Florida
Hawaii
MOBY Hawaii
Lake Titicaca
Galapagos
Eastern Med.
strait of Hormuz
Caspian Sea
Chesapeake
Western Australia
French Polynesia
Cook Straight - New
Zealand
Java Sea
Red Sea
Cuba - Jamaica
Cuba - Jamaica Fiji - Center
Zaire Congo River
Fiji - West
Java Sea
Lake Malawi
Gulf of Aden
(LIEOs)
(UFOs) Peru Upwelling
Peru Upwelling
Peru Upwelling Tahiti
Peru Upwelling Tahiti
Peru Upwelling Tahiti Gulf of Aden Cook Straight
Peru Upwelling Tahiti Gulf of Aden Cook Straight Bangladesh
Peru Upwelling Tahiti Gulf of Aden Cook Straight Bangladesh Panama
Peru Upwelling Tahiti Gulf of Aden Cook Straight Bangladesh Panama Ganges
Peru Upwelling Tahiti Gulf of Aden Cook Straight Bangladesh Panama Ganges Congo River
Peru Upwelling Tahiti Gulf of Aden Cook Straight Bangladesh Panama Ganges Congo River Ganges
Peru Upwelling Tahiti Gulf of Aden Cook Straight Bangladesh Panama Ganges Congo River Ganges Vietnam
Peru Upwelling Tahiti Gulf of Aden Cook Straight Bangladesh Panama Ganges Congo River Ganges

southwest australia

south georgia
Torres Straight
Shark Bay
Bali Sea
Gulf of Aden
Namibia
Bora Bora
Argentina
Aegean Sea
Chesapeake Bay
Christmas Island
Kerguelen Island
Orinoco Delta
Great Barrier Reef
Cameroon
Lake Baikal
Gulf of Khambhat
Western Nova
Scotia
Valdes Peninsula
Baleric Sea Gold Coast Australia
Gold Coast Australia
Sydney Australia
Ganges Mouth
Greece
San Franciso Bay
Japan
Red Sea
Big Island Hawaii
Sri Lanka
Adelaide Aust
Falklands
Spencer Gulf Aust
Western Black Sea
Western Black Sea Andaman Islands
Cook Straight
Long Island Sound
Fraser Island Aust
Ganges
Samoa
Gulf of Tehuantepec

Kodiak **Gulf of Carpentaria** Tasmania **English Channel Chesapeake Outer** Banks **Big Island Hawaii** Samoa East Northwest Australia **Southern Florida** Lake Titicaca Israel – Jordan **French Polynesia Coastal Peru Gulf of Khambhat Ayres Rock Aust** San Francisco

Image Acquisition Requests

https://uncw.edu/socon/image_request.html

Request SeaHawk Image Acquisition

Step 4

